

Linear Kernels for Graphs Excluding a Topological Minor

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Reduction via protrusions

(Topological) Minors

Our result and how it works

Conclusion

Linear kernels in sparse graphs

Overview

- **Dominating Set in planar graphs**
Alber, Fellows, Niedermeier. *Polynomial-time data reduction for Dominating Set*, 2004.
- **Framework for planar graphs**
Guo and Niedermeier: *Linear problem kernels for NP-hard problems on planar graphs*, 2007.
- **Meta-result for graphs of bounded genus**
Bodlaender, Fomin, Lokshtanov, Penninkx, Saurabh and Thilikos: *(Meta) Kernelization*, 2009.
- **Meta-result for graphs excluding a fixed graph as a minor**
Fomin, Lokshtanov, Saurabh and Thilikos: *Bidimensionality and kernels*, 2010.
- **Our contribution:** a meta-result for graphs excluding a fixed graph as a *topological minor*.

Main theorem

Theorem

Let Π be a parameterized graph problem that has

- 1 *finite integer index, and*
- 2 *is treewidth-bounding,*

both on the class of \mathbb{H} -topological-minor-free graphs. Then Π admits a linear kernel.

The undefined terms

- 1 A **parameterized graph problem** Π is a set of pairs (G, k) , where G is a graph and k a non-negative integer s.t.

$$G_1 \cong G_2 \text{ implies } (G_1, k) \in \Pi \text{ iff } (G_2, k) \in \Pi.$$

- 2 A parameterized graph problem Π is **treewidth-bounding** if \exists constants c, t such that $(G, k) \in \Pi$ implies that

$$\exists X \subseteq V(G) \text{ s.t. } |X| \leq c \cdot k \text{ and } \mathbf{tw}(G - X) \leq t.$$

- 3 The property of **finite integer index** allows us to replace large “protrusions” by smaller gadgets.

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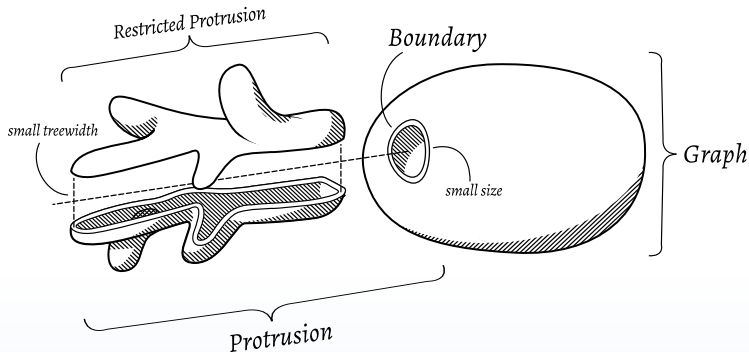
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- 3 The property of **finite integer index** allows us to replace large “protrusions” by smaller gadgets.

We assume that the gadgets are given. Our algorithm is nonuniform.

Reduction via protrusions

Protrusion anatomy



Definition

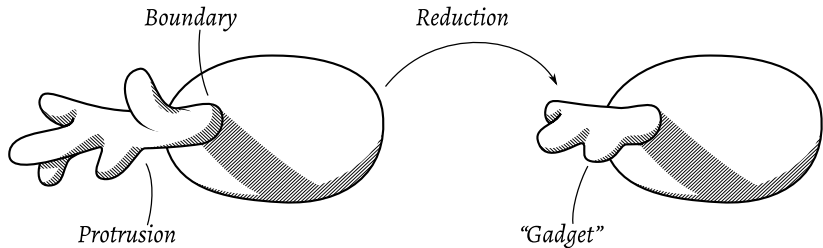
$X \subseteq V(G)$ is a t -protrusion if

① $|\partial(X)| = |N(X) \setminus X| \leq t$

(small boundary)

② $\mathbf{tw}(G[X]) \leq t$

(small treewidth)



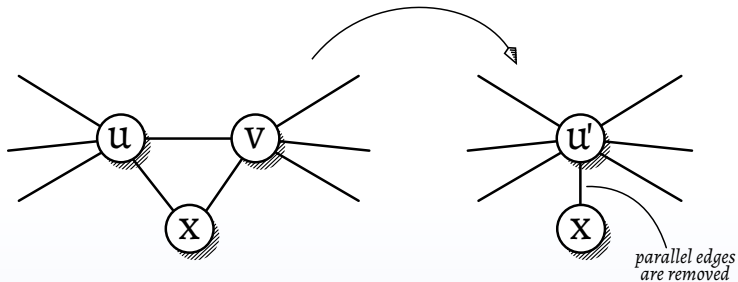
We want to replace a large protrusion by a smaller gadget.

- 1 Requires that the problem has finite integer index.
- 2 The gadgets can always be chosen such that the parameter does *not* increase.
- 3 This is the only reduction.

(Topological) Minors

Edge contraction

Contracting uv



Graph relations

(now with contractions!)

Graph relations

(now with contractions!)

Relation

Operations

induced subgraph

delete vertices

subgraph

topological minor

minor

Graph relations

(now with contractions!)

Relation

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delete vertices and edges

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Graph relations

(now with contractions!)

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delete vertices and edges,
contract edges

Graph relations

(now with contractions!)

Relation

Operations

induced subgraph

delete vertices

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delete vertices and edges

topological minor

take a subgraph, contract edges *incident to a degree-2 vertex*

minor

delete vertices and edges, contract edges

Properties of H-topological-minor-free graphs

Let G be a graph excluding H as a topological minor.

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- In particular: K_r not a topological minor of G .

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Important properties:

- 1 $m \leq \frac{1}{2}\beta r^2 n$ (for some $\beta < 10$);
- 2 no. of cliques $\leq 2^{\tau r \log r} n$ (for some $\tau < 4.51$);
- 3 Closed under taking topological minors.

Our result and how it works

On the treewidth-bounding property

Definition (Treewidth bounding)

A parameterized graph problem Π is called *treewidth bounding* if \exists constants c, t such that for every $(G, k) \in \Pi$, $\exists S \subseteq V(G)$ s.t.

- 1 $|S| \leq ck$;
- 2 $\text{tw}(G - S) \leq t$.

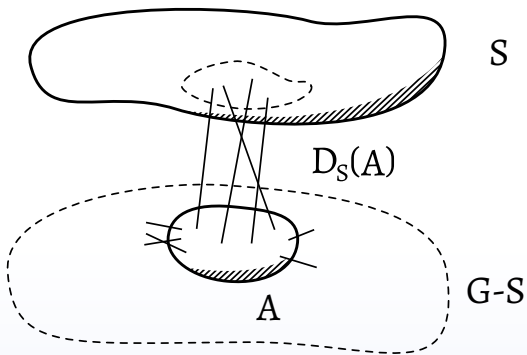
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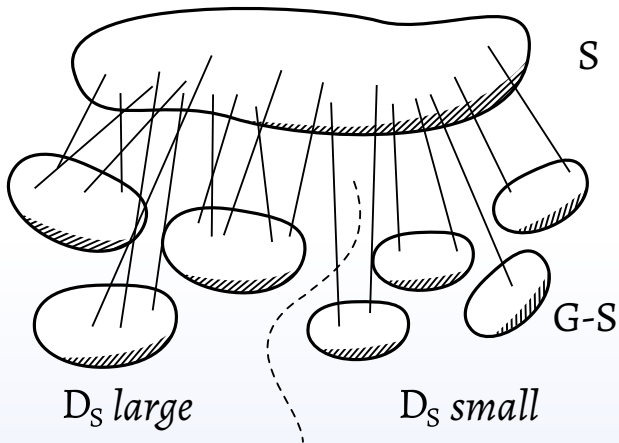
- 1 $|S| \leq ck$;
 - 2 $\text{tw}(G - S) \leq t$.
- S usually is the solution set.
 - Vertex Cover, Feedback Vertex Set in general graphs.
 - Chordal Vertex Deletion in graphs with bounded clique-size.

A little bit of notation

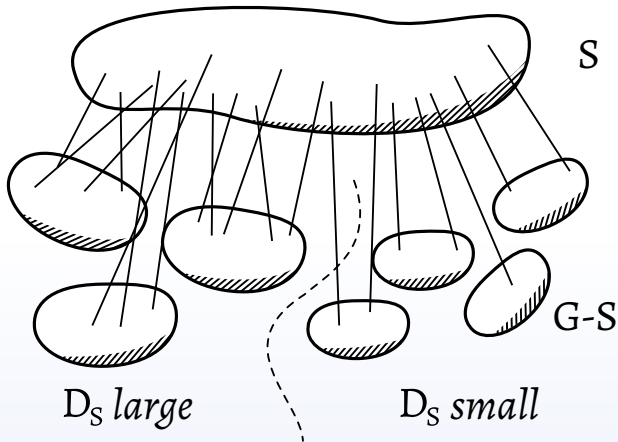


For disjoint vertex sets $S, A \in V(G)$, $D_S(A) = |N_G(A) \cap S|$.

A decomposition

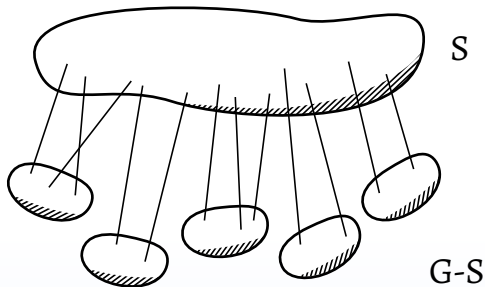


A decomposition



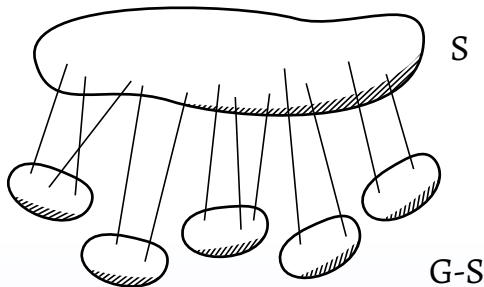
Reduced instance: large protrusions are gone

Small-degree components



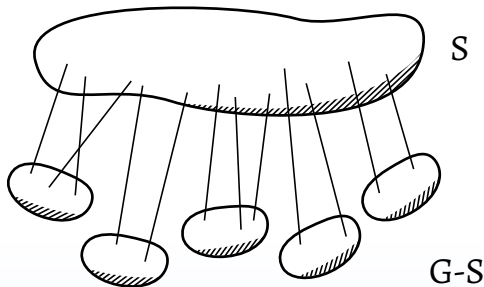
- $D_S(C) < r$, therefore each component C has a boundary of size r .

Small-degree components



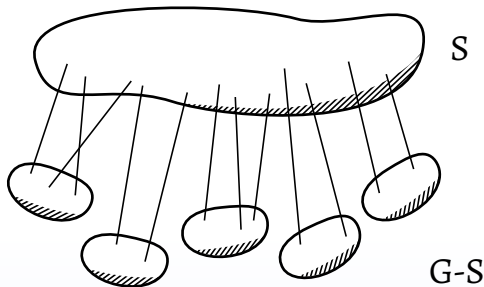
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- C has constant treewidth (problem is treewidth bounding).

Small-degree components



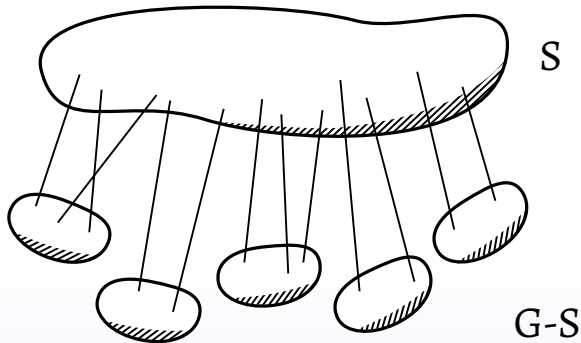
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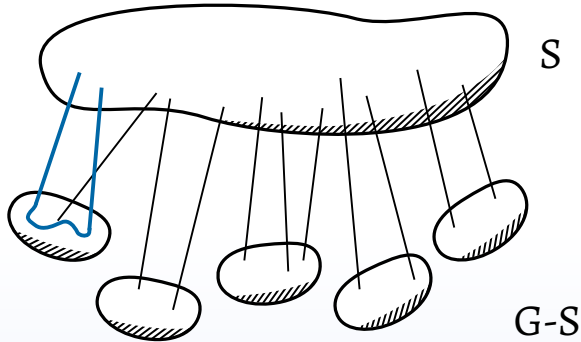


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 - C has constant treewidth (problem is treewidth bounding).
- ⇒ Each small-degree component has constant size (reduced instance).
- What about the *number* of small-degree components?

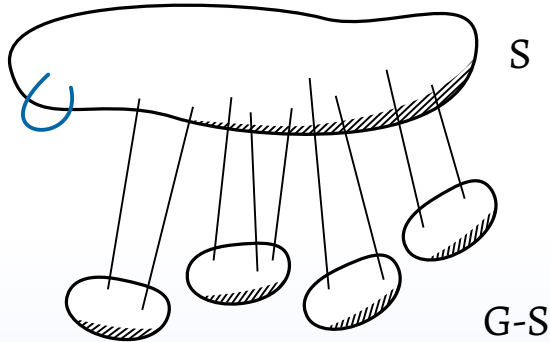
Small-degree components



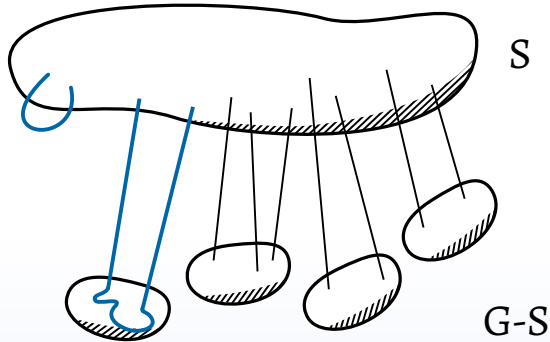
Small-degree components



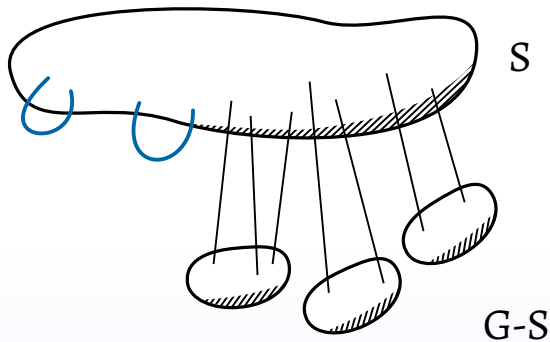
Small-degree components



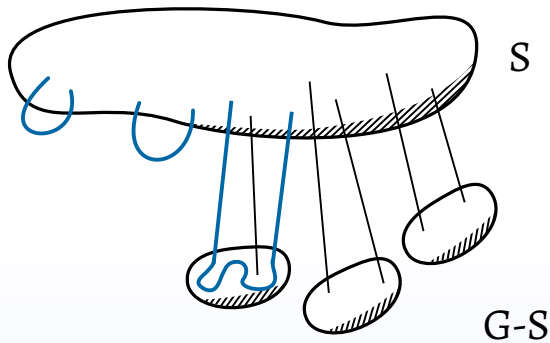
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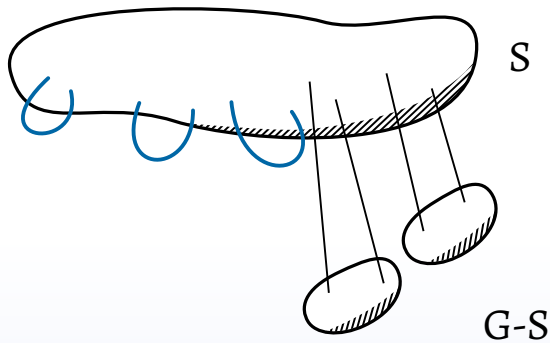
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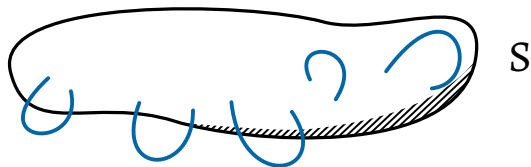
Small-degree components



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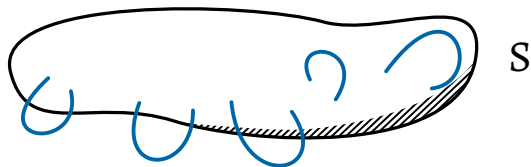


Small-degree components



G-S

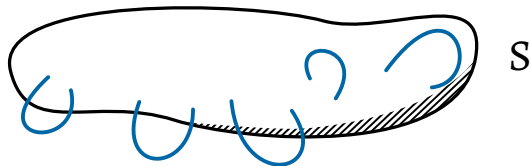
Small-degree components



G-S

- How often can we do this?

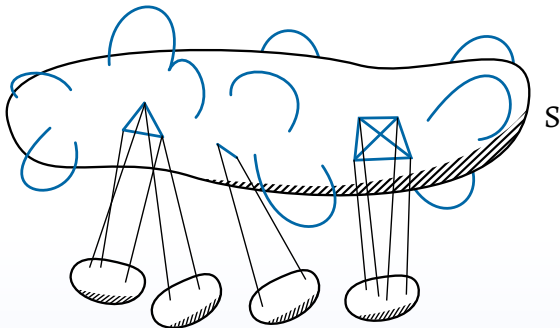
Small-degree components



G-S

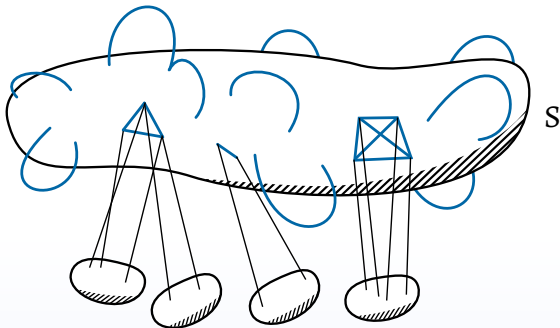
- How often can we do this?
- Is it exhaustive?

Small-degree components



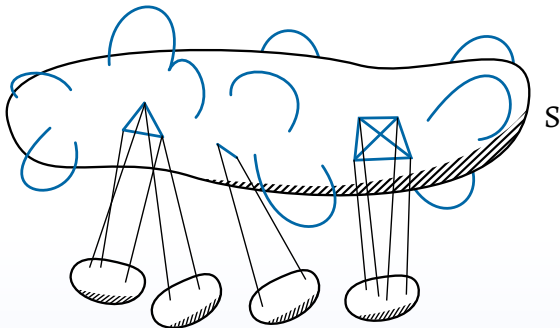
- Components now connected to cliques (or not finished)

Small-degree components



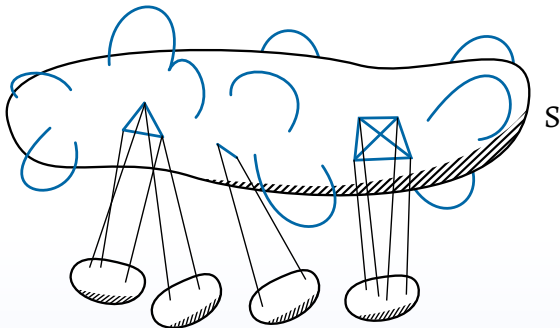
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Small-degree components



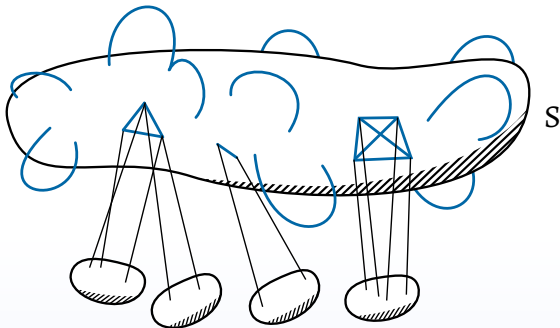
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Small-degree components



- Components now connected to cliques (or not finished)
- $G[S]$ is H -topological minor free, therefore...
 - ... $O(|S|) = O(k)$ cliques
 - ... $O(|S|) = O(k)$ edges
- Constant number of vertices in components connected to a common clique (or large protrusion in G)

Total size of small degree components

$O(k)$ vertices in small-degree components.

Large-degree components

Two ingredients:

Large-degree components

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- 1 At most $O(k)$ connected *subgraphs* with $D_S \geq r$.

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 - of **constant size**; and
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Since there are $O(k)$ such subgraphs, their total size is $O(k)$.

Large-degree components

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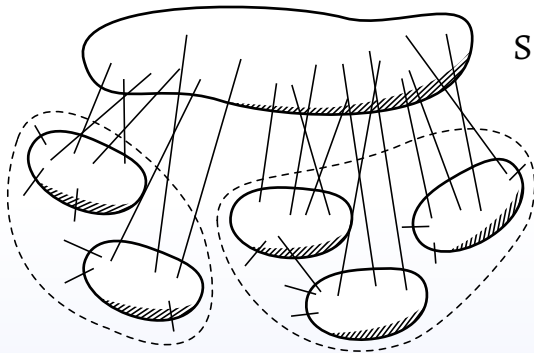
Our proof that such a decomposition exists is very technical.

A simplification of our proof appears in:

A parameterized single-exponential algorithm for hitting planar minors. Kim, Paul, and Sau.

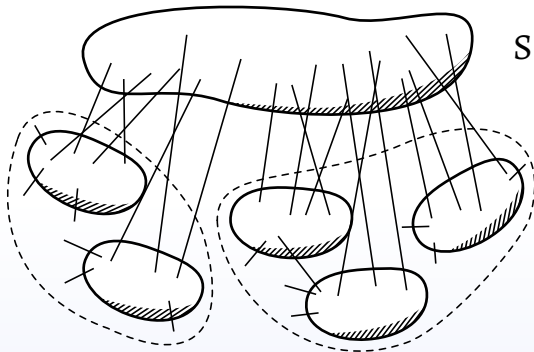
Large-degree components

Ingredient one



Large-degree components

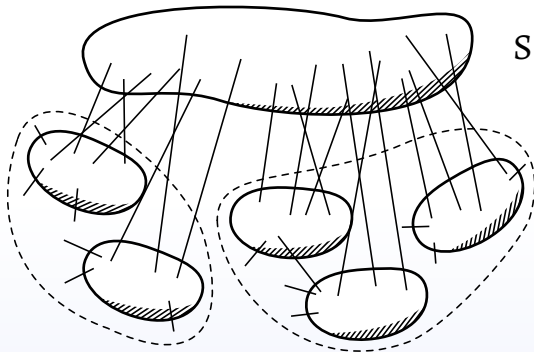
Ingredient one



- Same idea as before: contract connected subgraphs into edges in S

Large-degree components

Ingredient one



- Same idea as before: contract connected subgraphs into edges in S
- Exhaustive, else K_r as a subgraph in S and thus H as a topological minor in G

Large-degree components

Ingredient two

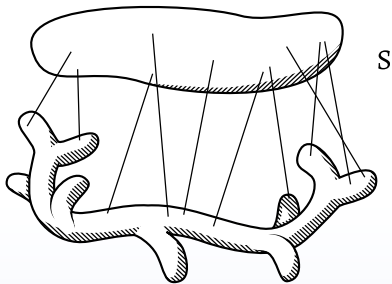
Every large-degree component can be broken into:

- path-like structures (paths in a tree-decomposition);
- star-like structures (join nodes in a tree-decomposition).

We use tree-decompositions to effect such a break-up.

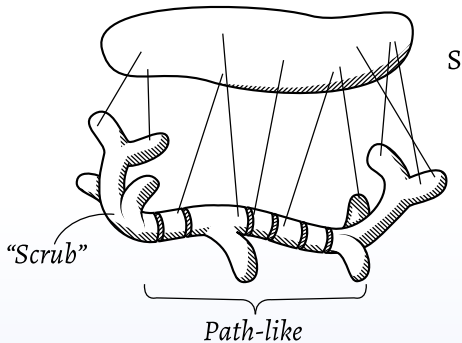
Large-degree components

Ingredient two



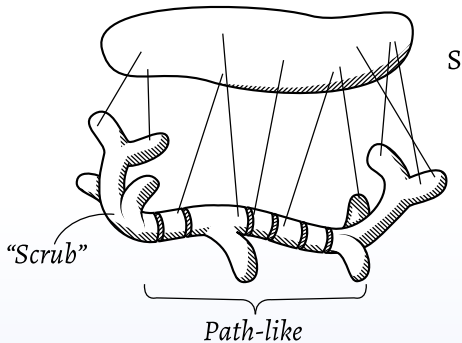
Large-degree components

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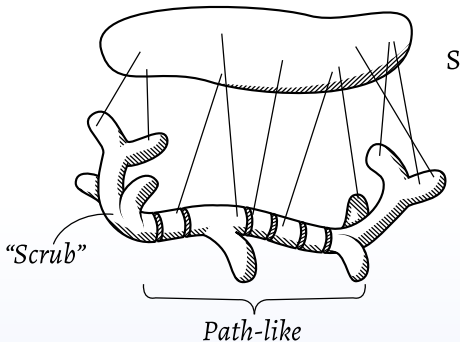
Ingredient two



- Walk along path-decomposition.

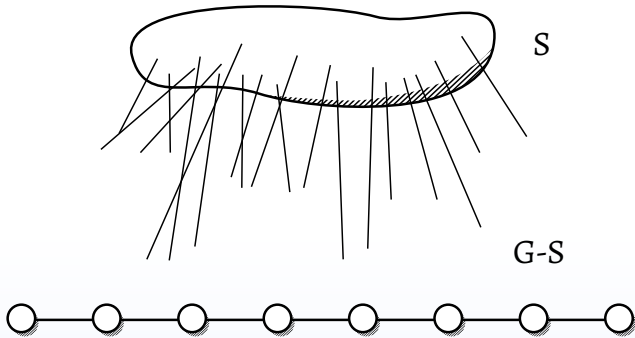
Large-degree components

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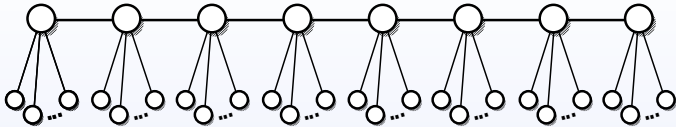
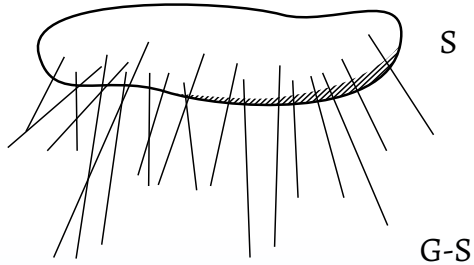


- Walk along path-decomposition.
- If more than $\omega(2t + r)$ vertices seen: subgraph has large degree wrt S .

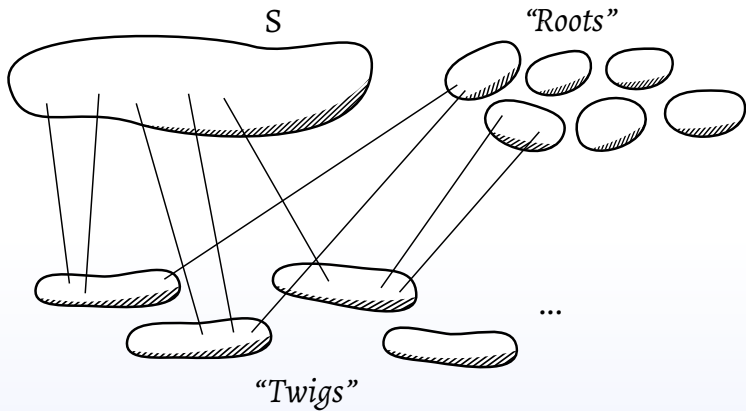
Examples



Examples



Examples



Conclusion

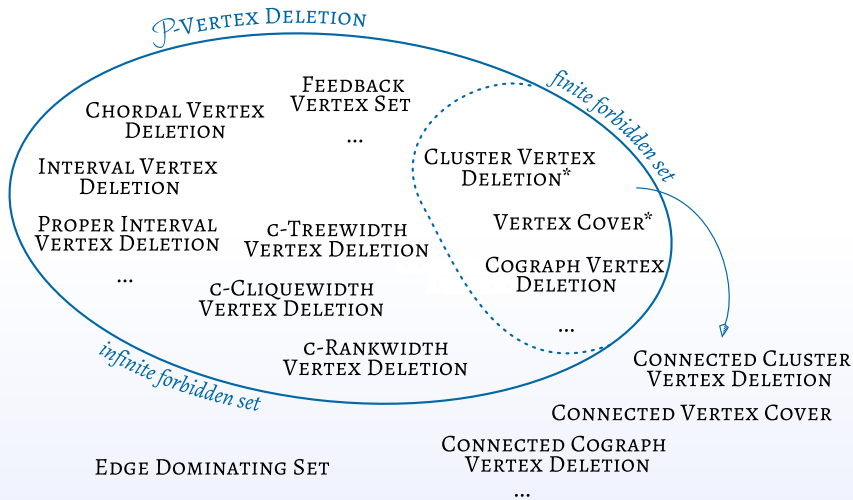
The result

Parameterized graph problems that have

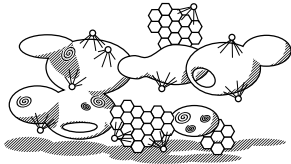
- 1 finite integer index, and are
- 2 treewidth bounding,

admit linear kernels on graphs excluding a fixed topological minor.

Examples

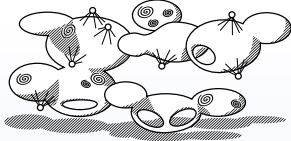


Trade-off: class of instances vs. problem requirements



*H-Topological-
Minor-Free*

Treewidth-bounding



H-Minor-Free

*Bidimensional
+ separation property*



Bounded Genus

Quasi-compact



Planar

“Distance-property”

Open questions

- What about graphs excluding a fixed **induced minor**? What other notions of sparse graphs allow such a theorem?

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