# EFFICIENT FO-MODEL CHECKING ON BARABASI-ALBERT GRAPHS

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FO-logic (first order logic) is a powerful language to express problems in.

Recursive definition:

 $\bigcirc \varphi = \forall x \psi(x) \qquad \bigcirc \varphi = \varphi_1 \lor \varphi_2$  $\bigcirc \varphi = \exists x \psi(x) \qquad \bigcirc \varphi = \varphi_1 \land \varphi_2$  $\bigcirc \varphi = (u = v) \qquad \bigcirc \varphi = \neg \psi$  $\bigcirc \varphi = adj(u, v)$ 

 $G \models \varphi$ : Is *G* a model for  $\varphi$ ?

Example:  $\exists x \exists y \exists z (adj(x, y) \land adj(x, z) \land adj(y, z))$ 

- If  $\mathcal{G}$  has bounded treewidth, then we can decide  $G \models \varphi$  in linear time if  $G \in \mathcal{G}$  and  $\varphi$  is an MSO-formula. [Courcelle 1990]
- If  $\mathcal{G}$  has bounded expansion, then we can decide  $G \models \varphi$  in linear time if  $G \in \mathcal{G}$  and  $\varphi$  is an FO-formula. [Dvořák, Kráľ, Thomas 2010]
- If  $\mathcal{G}$  is nowhere dense, then we can decide  $G \models \varphi$  in time  $n^{1+\epsilon}$  if  $G \in \mathcal{G}$  and  $\varphi$  is an FO-formula. [Kreutzer, Grohe, Siebertz 2011]

When is an algorithm fast on random inputs?

- worst case running time?
- fast on  $1 \varepsilon$  fraction of inputs for small  $\varepsilon$ ?
- fast average running time  $\sum_{G \in \mathcal{G}}$  running time on input  $G \cdot$  probability of G.

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Expected running time:  $(1 - \varepsilon)f(k)n + \varepsilon n^k$ 

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Gaifman: If we can do model-checking on *r*-neighborhoods we can do it for the complete graph.



This is not enough.

Model-checking on bipartite graphs with log(n) vertices on the left as hard as the general case.

Problem: Vertices on the right can have many neighbors on the left.





We decompose the vertices into sets *A*, *B*, *C* such that:

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Then:

- 🔾 use Gaifman
- Kernelize neighborhood to size  $f(|\varphi|)$  polylog(n)
- Solve in time  $(f(|\varphi|) \operatorname{polylog}(n))^{|\varphi|} = O(n^{\varepsilon})$



#### Kernelization:

- Consider *r*-neighborhoods
- Prune redundant isomorphic subtrees in *C*
- Size:  $f(|\varphi|)$  polylog(n)





Input: Preferential attachement graph G and formula  $\varphi$ 

- Check if *G* has *A*-*B*-*C*-structure.
- $\bigcirc$  If not use  $n^{|\varphi|}$ -algorithm and exit. Otherwise proceed.
- Use Gaifman to restrict model-checking to neighborhoods.
- Build  $f(|\varphi|)$  polylog(*n*)-kernel for neighborhood.
- Solve in time  $(f(|\varphi|) \operatorname{polylog}(n))^{|\varphi|}$  for each neighborhood.

Probability of not having *A-B-C* structure is less likely than  $\frac{1}{n^{|\varphi|}}$ . Therefore, expected running time FPT.

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*r*-neighborhood with many edges implies small subgraph with many edges.

We show that small subgraphs with many edges are improbable.



Probability that vertices  $v_1, v_2, \ldots, v_k$  form dense subgraph is

$$s(v_1, v_2, \dots, v_k) = P(adj(v_1, v_2), adj(v_5, v_3), \dots)$$

One can show

$$P(adj(a,b)) \le \frac{1}{\sqrt{ab}}$$

Use union-bound as upper bound

$$\sum_{v_1=l}^n \sum_{v_2=l}^n \cdots \sum_{v_k=l}^n s(v_1, v_2, \dots, v_k)$$

This sum is small for  $l = \log(n)^{O(1)}$ .

We analyze fine structure of preferential attachment graphs to construct an efficient model-checking algorithm.

Possible future work: Generalize to other random graphs.