

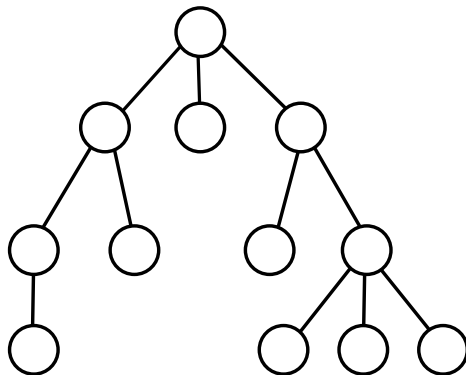
# Computing Treedepth

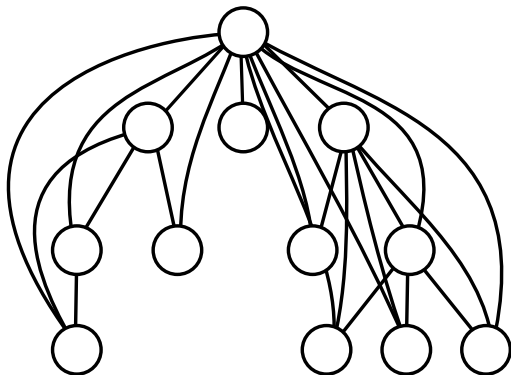
Felix Reidl, Peter Rossmanith, **Fernando Sánchez Villaamil**  
Somnath Sikdar

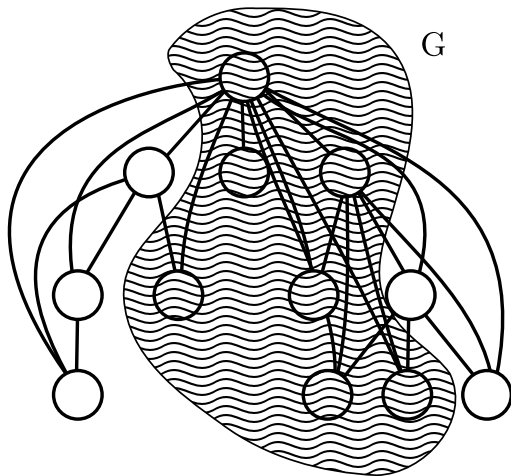
RWTH Aachen

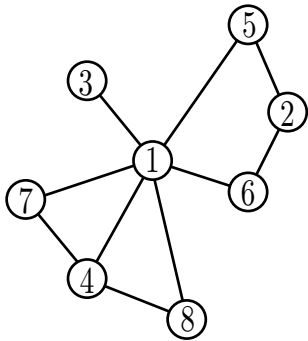
March 14, 2014

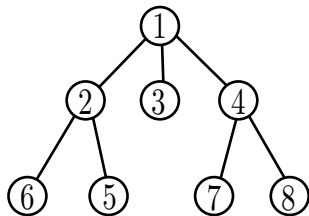
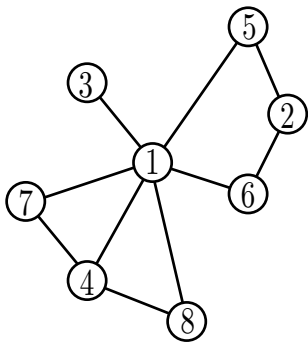
Treedepth is a width measure.

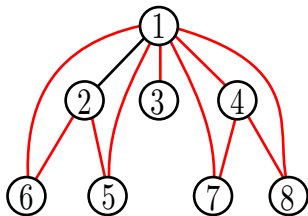
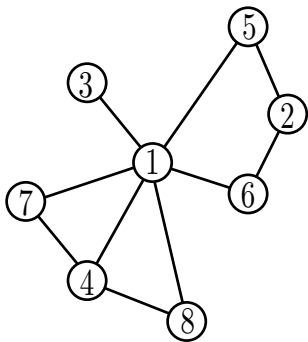




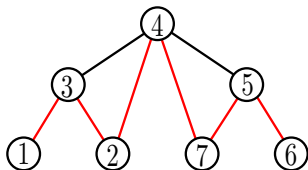
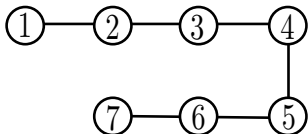






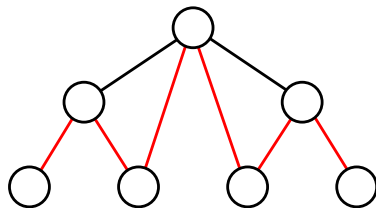
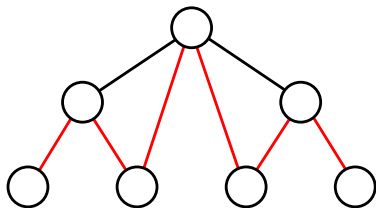




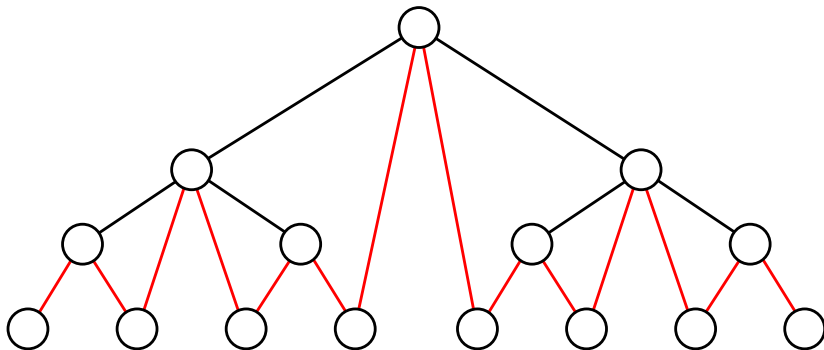


Treedepth  $t \rightarrow$  Maximal path length  $2^t - 1$ .

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### Definition (Treedepth decomposition)

A *treedepth decomposition* of a graph  $G$  is a rooted forest  $F$  such that  $V(G) \subseteq V(F)$  and  $E(G) \subseteq E(\text{clos}(F))$ .

### Definition (Treedepth)

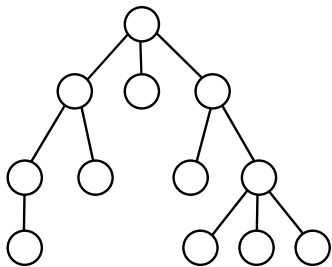
The *treedepth*  $\mathbf{td}(G)$  of a graph  $G$  is the minimum height of any treedepth decomposition of  $G$ .

# Equivalent notions

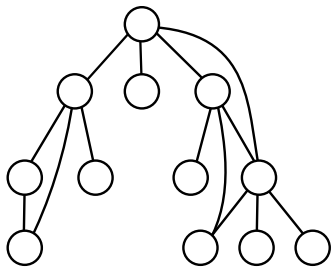
A graph  $G$  has treedepth at most  $t$  if and only if:

- $G$  is a subgraph the closure of a tree (forest) of height  $t$
- $G$  is the subgraph of a trivially perfect graph with clique size at most  $t$
- $G$  has a centered coloring with  $t$  colors
- $G$  has a ranked coloring with  $t$  colors

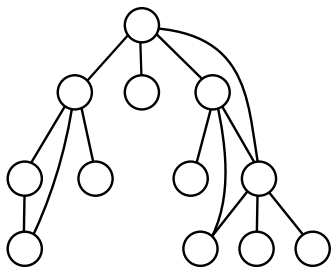
# A DFS is a Treedepth decomposition



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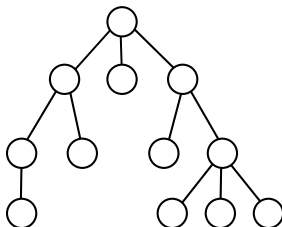
# A DFS is a Treedepth decomposition



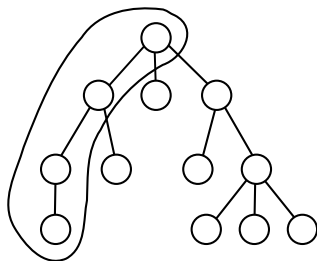
Treedepth  $t \Rightarrow$  Maximal path length  $2^t - 1 \Rightarrow 2^t$ -approximation



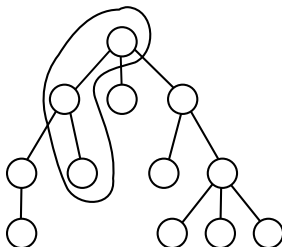
# Treedepth to pathwidth



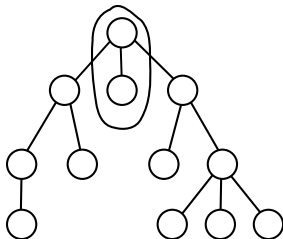
# Treedepth to pathwidth



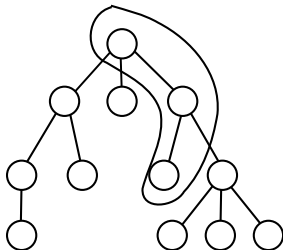
# Treedepth to pathwidth



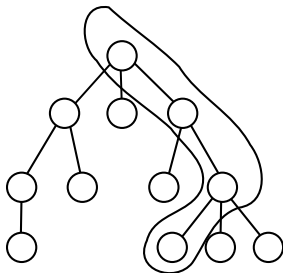
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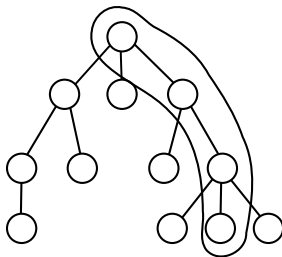
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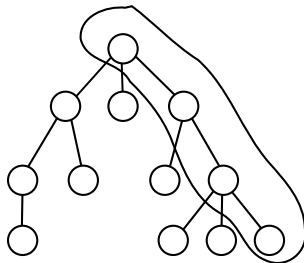
# Treedepth to pathwidth



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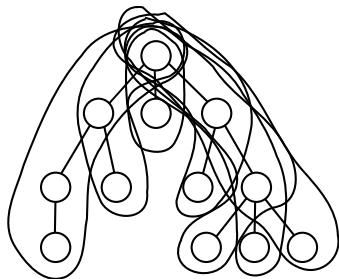


# Treedepth to pathwidth

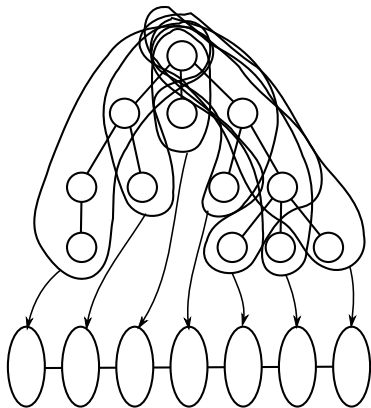




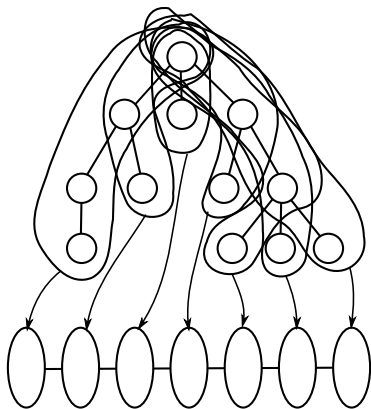
# Treedepth to pathwidth



# Treedepth to pathwidth



# Treedepth to pathwidth



$$\mathbf{tw}(G) \leq \mathbf{pw}(G) \leq \mathbf{td}(G) - 1$$

Treedepth  $t \Rightarrow$  Path decomposition of width  $2^t - 2$

Known ways to compute the treewidth of a graph:

- In  $f(t) \cdot n^3$  time by Robertson and Seymour.
- $\text{tw}(G) \leq \text{td}(G) - 1 \Rightarrow$  By Courcelle's Theorem  $2^{2^{2^{\dots^t}}} \cdot n$ .
- Algorithm by Bodlaender et. al. with running time  $2^{O(w^2t)} \cdot n^2$ .

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## Problem

*Is there a simple linear time algorithm to check  $\text{td}(G) \leq t$  for fixed  $t$ ?*

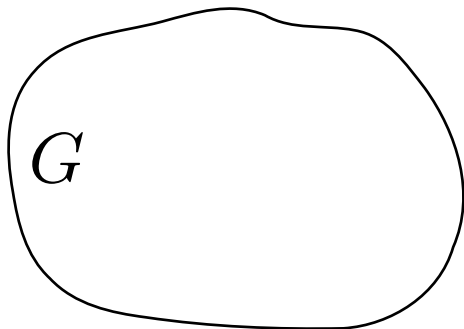
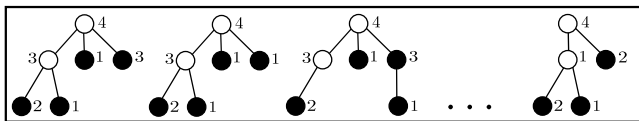
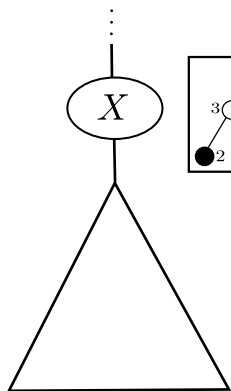
Our results:

- A (relatively) simple direct algorithm in time  $2^{2^{O(t)}} \cdot n$ .
- A fast algorithm in time  $2^{O(t^2)} \cdot n$ .

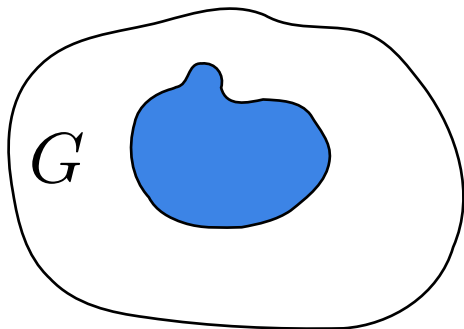
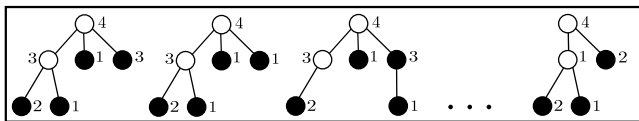
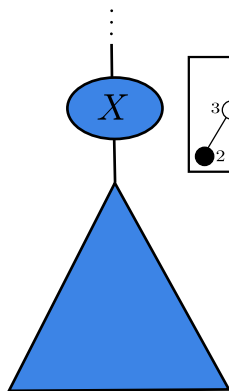
Our results:

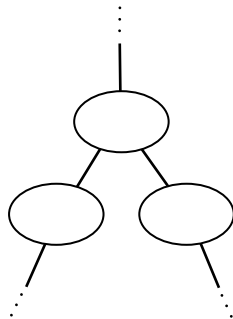
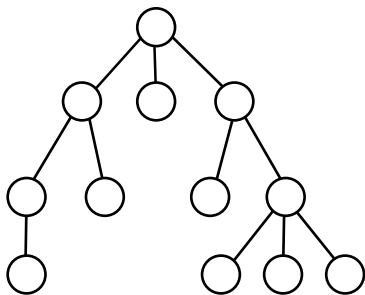
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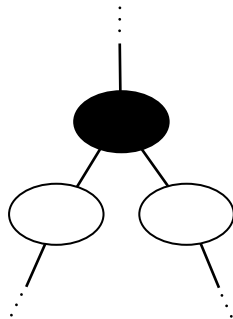
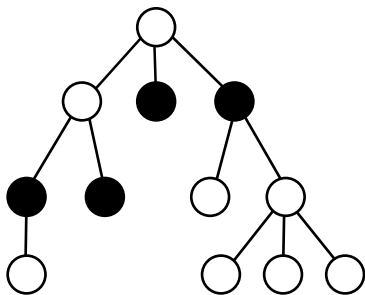
Both results follow from an algorithm on tree decompositions which runs in time  $2^{O(wt)} \cdot n$ .

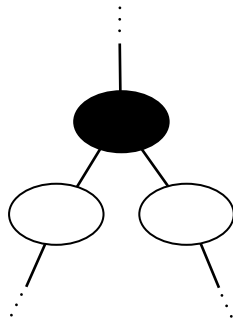
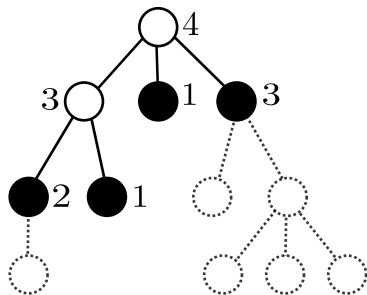


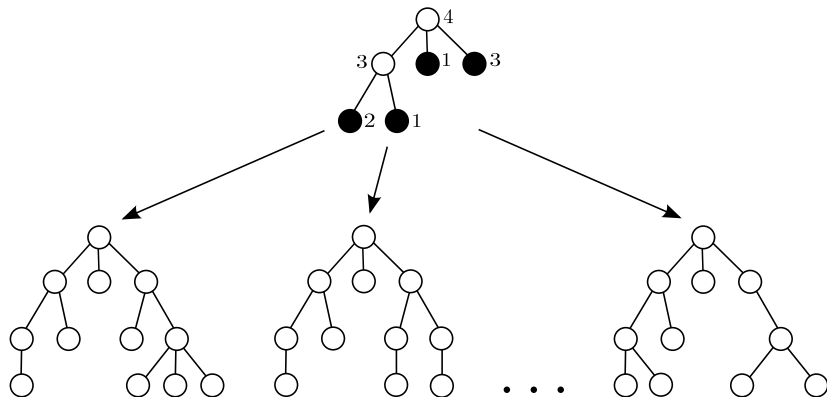


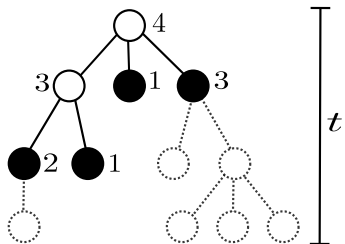


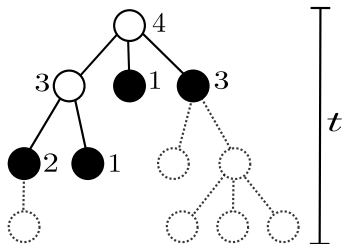




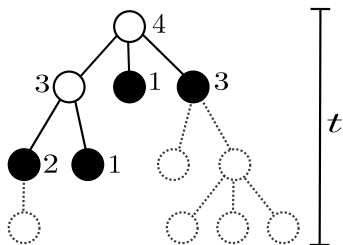








Any partial decomposition has less than  $wt$  nodes.



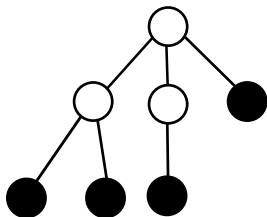
Any partial decomposition has less than  $wt$  nodes.

## Counting

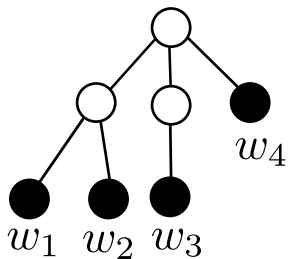
- How many trees with labeled leaves?
- How many height labelings per tree?



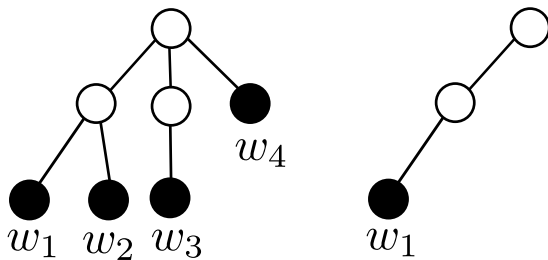
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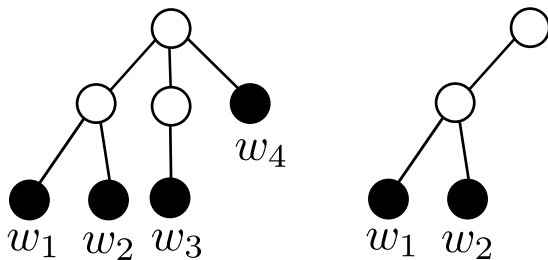
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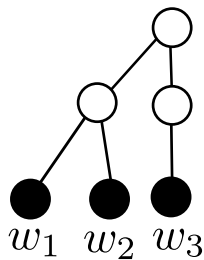
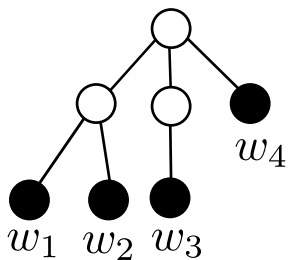
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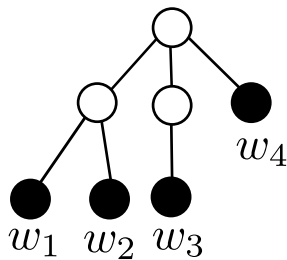
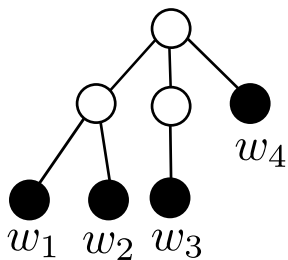
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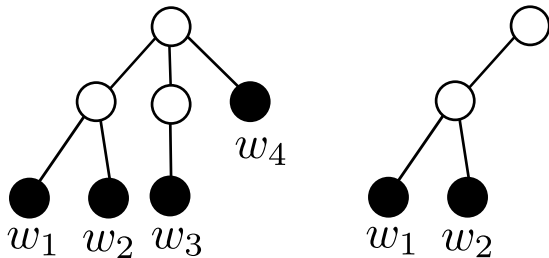
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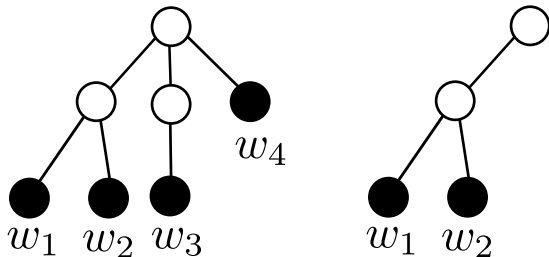
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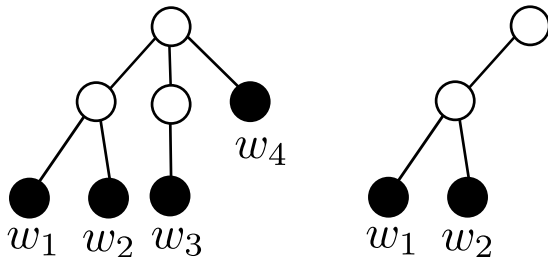
# How many trees with labeled leaves?



$$\prod_{i=1}^w it \cdot t$$

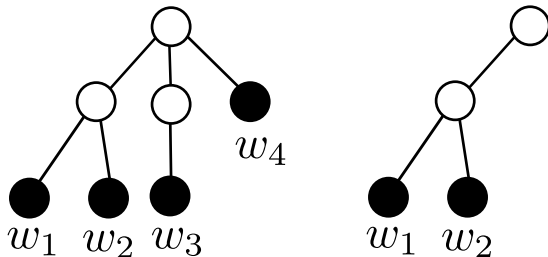


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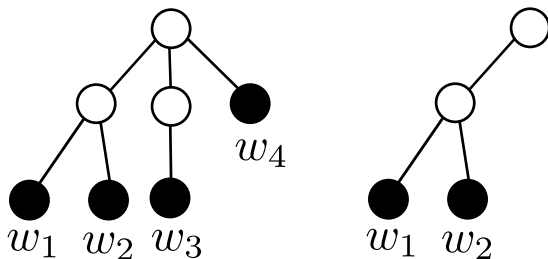
$$\prod_{i=1}^w it \cdot t \leq w! \cdot t^{2w}$$

# How many trees with labeled leaves?



$$\prod_{i=1}^w it \cdot t \leq w! \cdot t^{2w} \leq 2^{2w \log t + w \log w}$$

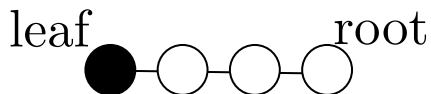
# How many trees with labeled leaves?



$$\prod_{i=1}^w it \cdot t \leq w! \cdot t^{2w} \leq 2^{2w \log t + w \log w} = 2^{O(wt)}$$

# How many height labelings per tree?

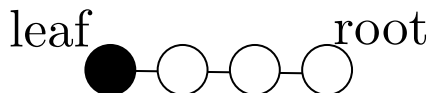
How many labeling can a path have?



$(1, 2, 3, 4, 5, 6, \dots, t)$

# How many height labelings per tree?

How many labeling can a path have?

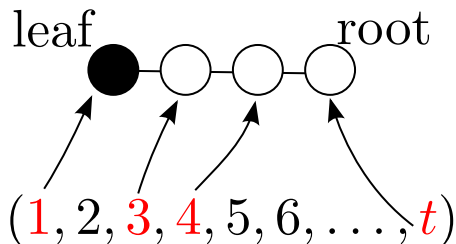


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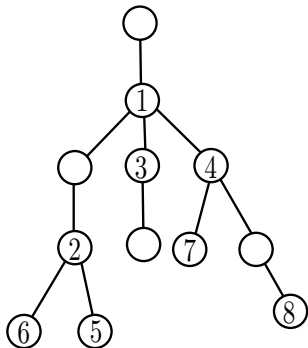
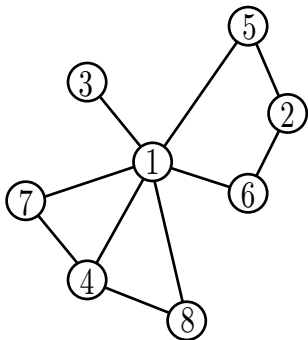


$$(2^t)^w = 2^{O(wt)}$$

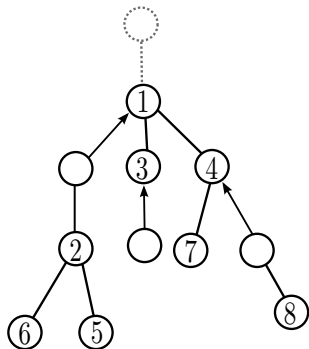
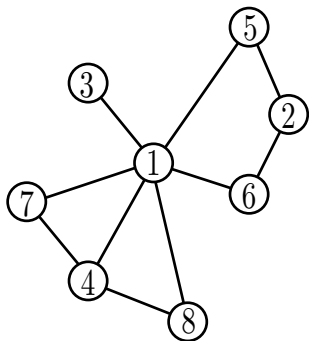
The total number of labeled trees is  $2^{O(wt)} \cdot 2^{O(wt)} = 2^{O(wt)}$ .



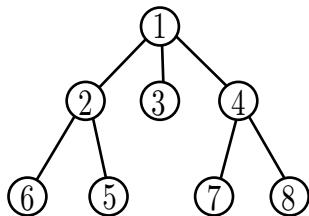
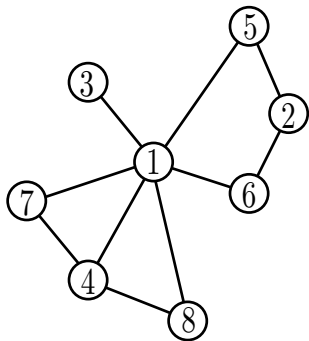
# Non-trivially improvable treedepth decompositions

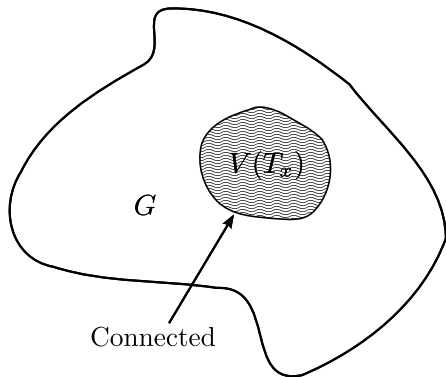
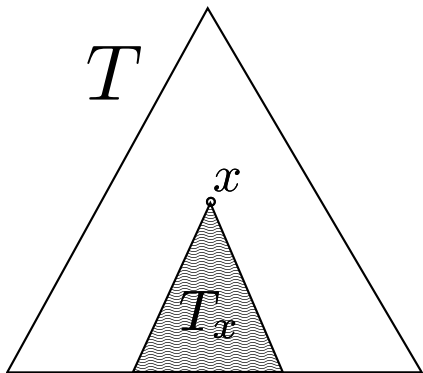


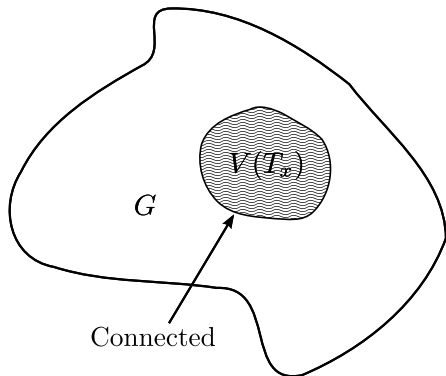
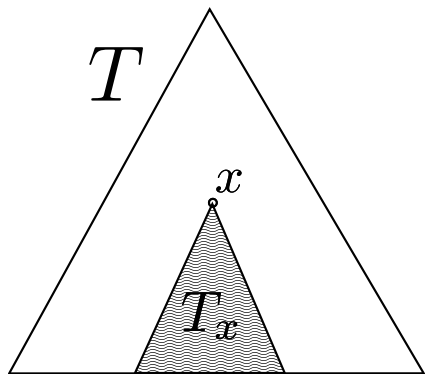
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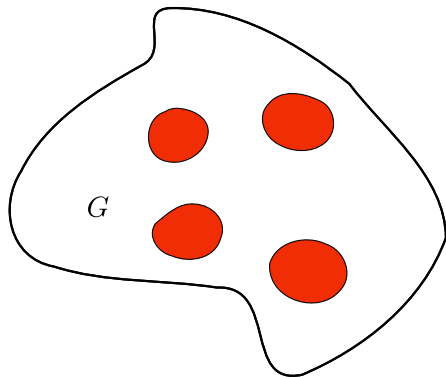
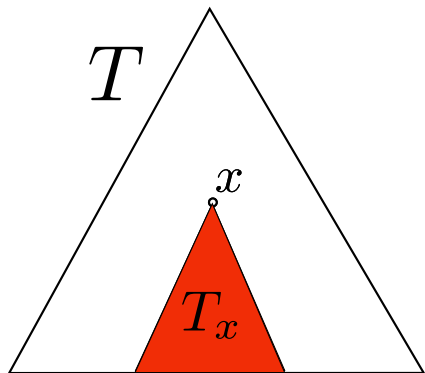


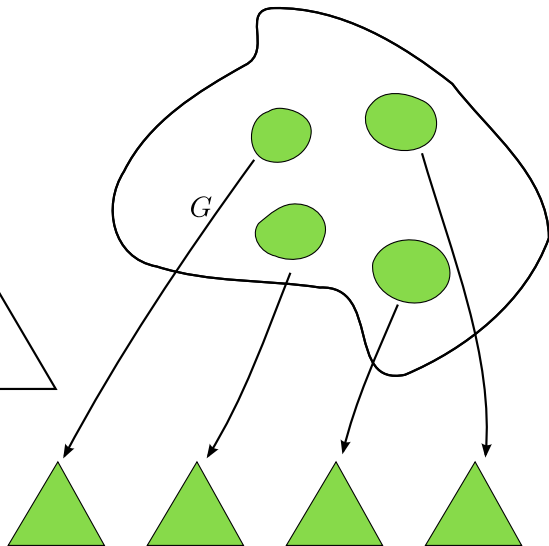
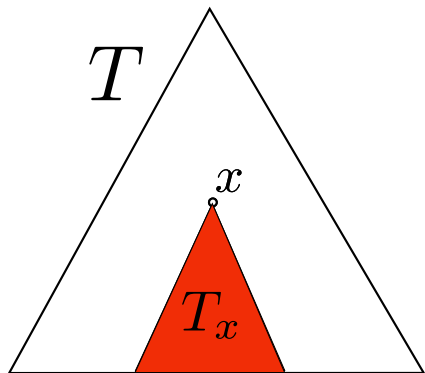


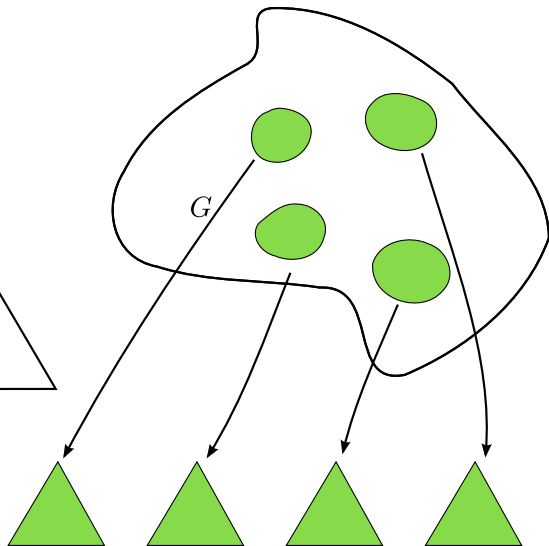
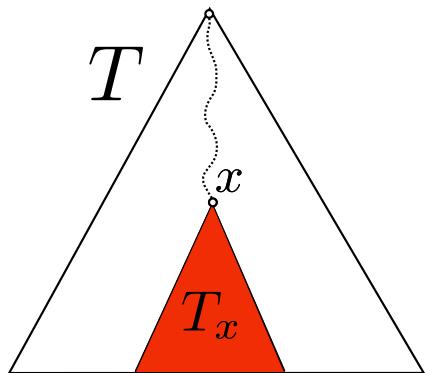


### Definition (Nice treedepth decomposition)

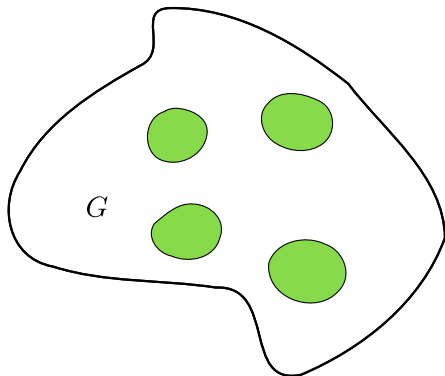
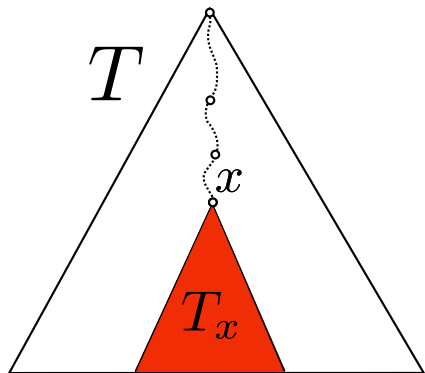
Consider a treedepth decomposition  $T$  of  $G$  that is not trivially improvable. We say that  $T$  is *nice* if for every vertex  $x \in V(T)$ , the subgraph of  $G$  induced by the vertices in  $T_x$  is connected.

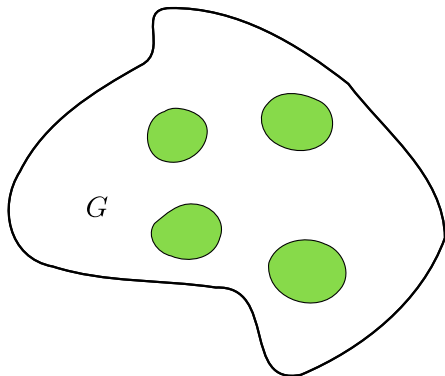
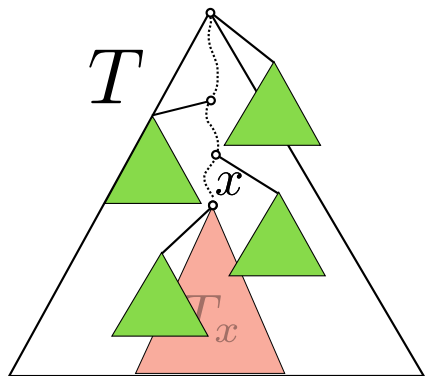








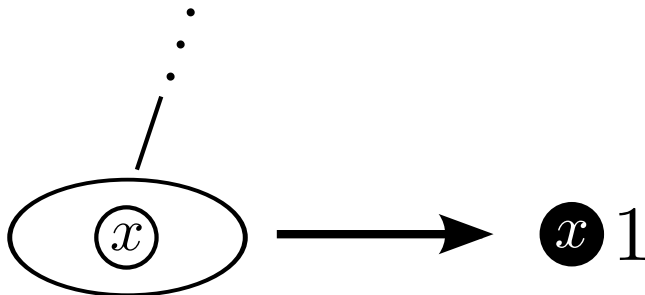




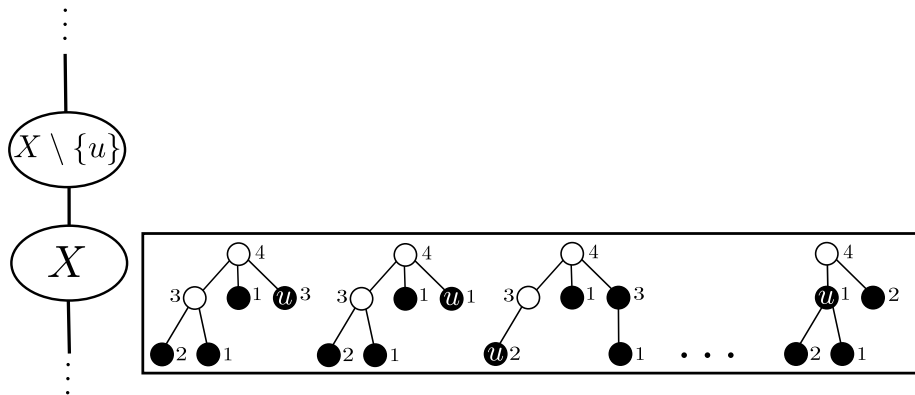
## Lemma

*For any graph there exists a treedepth decomposition of minimal depth which is nice and non-trivially improvable.*

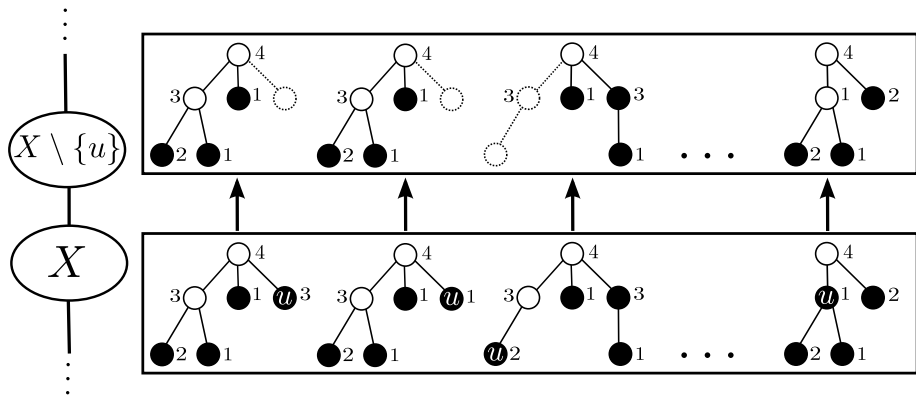
## Leaf



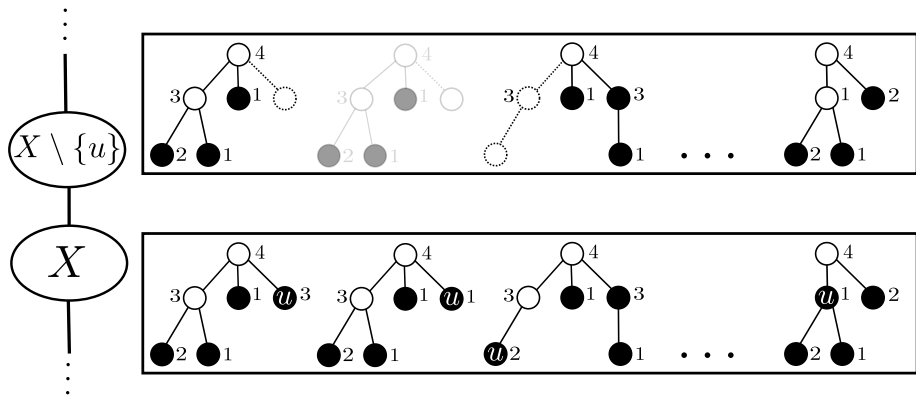
## Forget



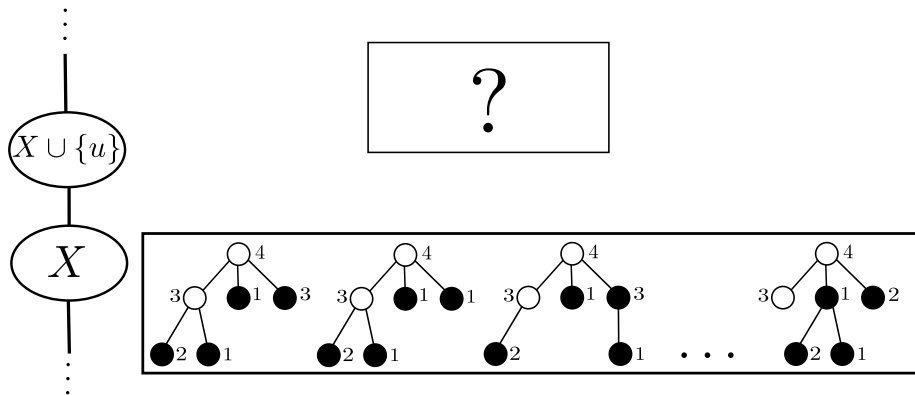
## Forget



## Forget



## Introduce



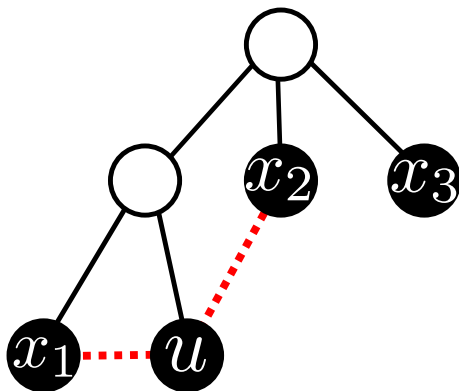


# Introduce

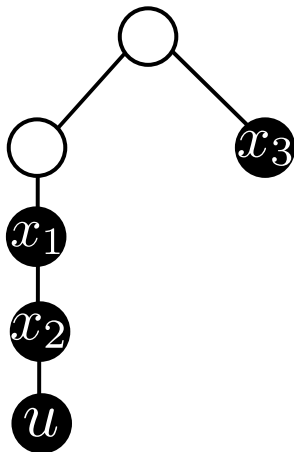
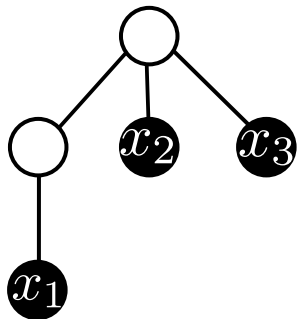
- 1 We guess every tree  $T$  with the following conditions:
  - ▶  $X \cup \{u\} \subseteq V(T)$ ,
  - ▶ All leaves are in  $X \cup \{u\}$ ,
  - ▶ Height at most  $t$ .
- 2 We keep some, dismiss others.

# Introduce

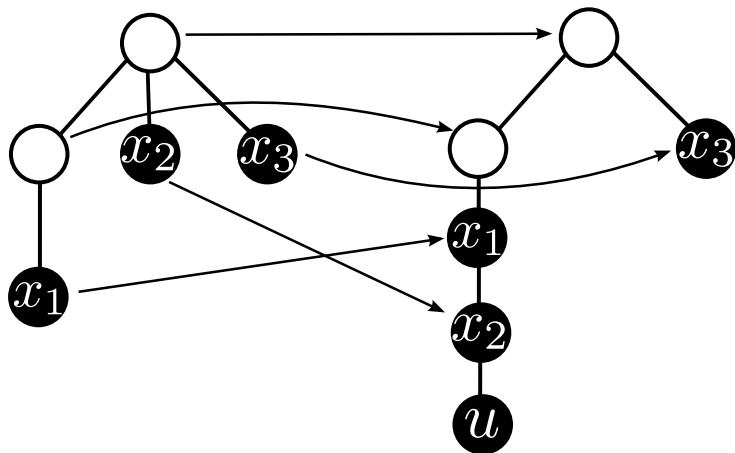
Throw away if edges of  $X$  are missing



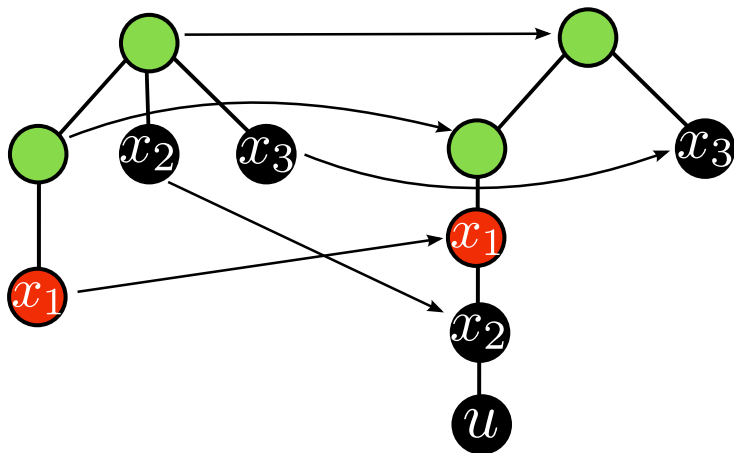
# Topological generalization



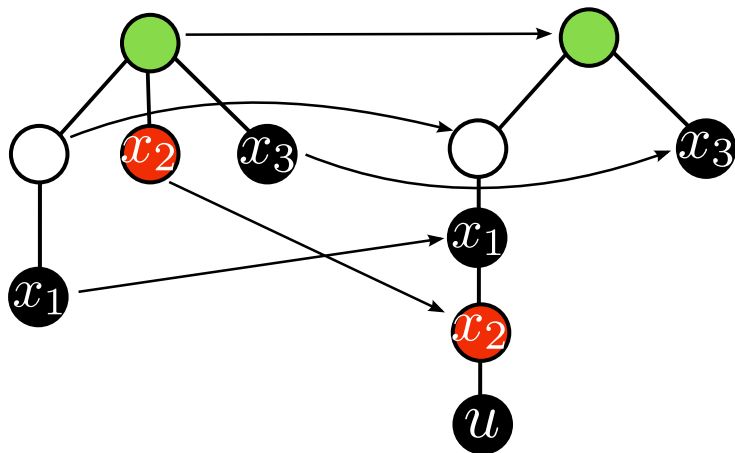
# Topological generalization



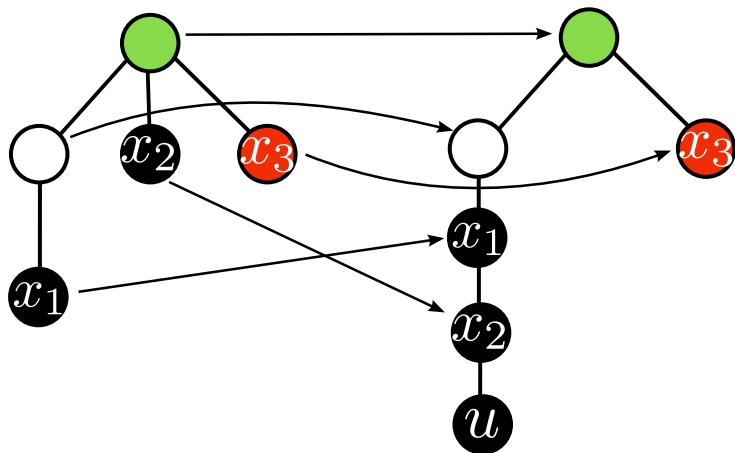
# Topological generalization



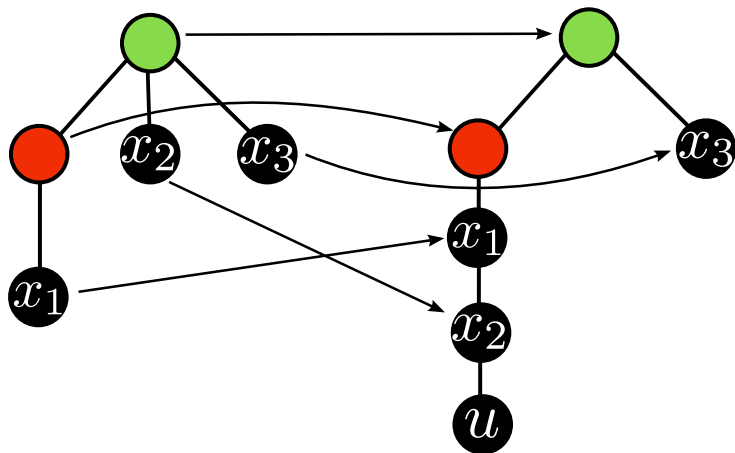
# Topological generalization



# Topological generalization

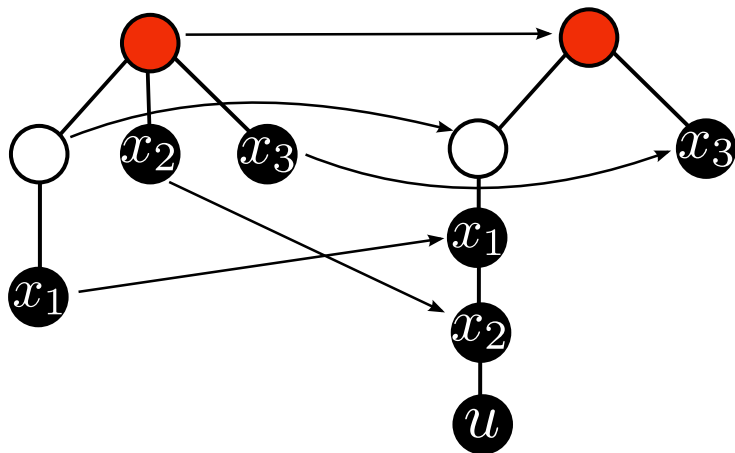


# Topological generalization





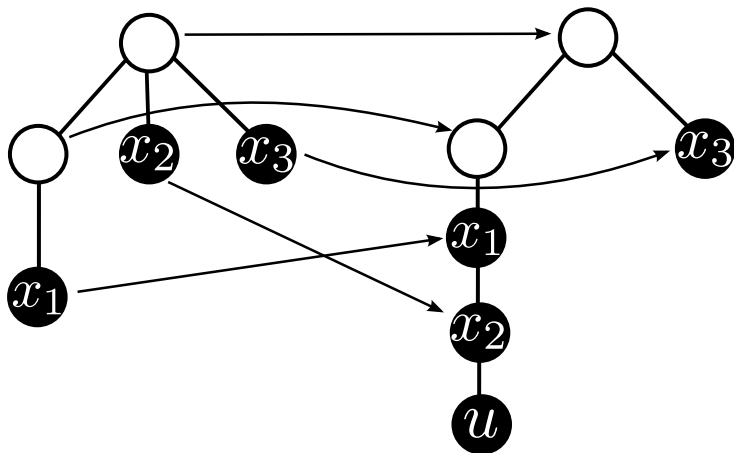
# Topological generalization



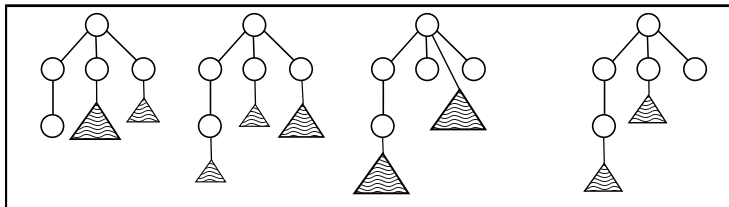
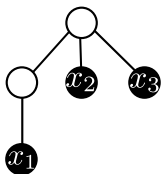
# Introduce

- 1 Guess tree with certain conditions:
  - ▶  $X \cup \{u\} \subseteq V(T)$ ,
  - ▶ All leaves are in  $X \cup \{u\}$ ,
  - ▶ Height at most  $t$ .
- 2 If edge missing between nodes of  $X \cup \{u\}$ , discard.
- 3 If not a topological generalization of an element in old table, discard.

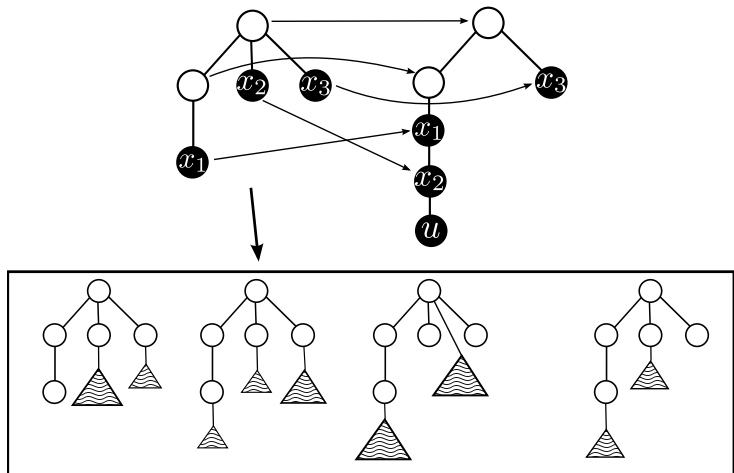
# Why should this work?



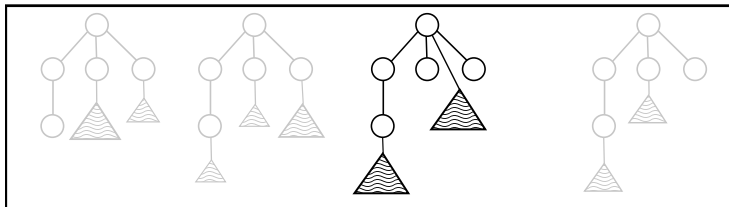
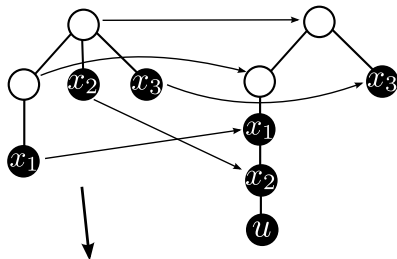
# Why should this work?



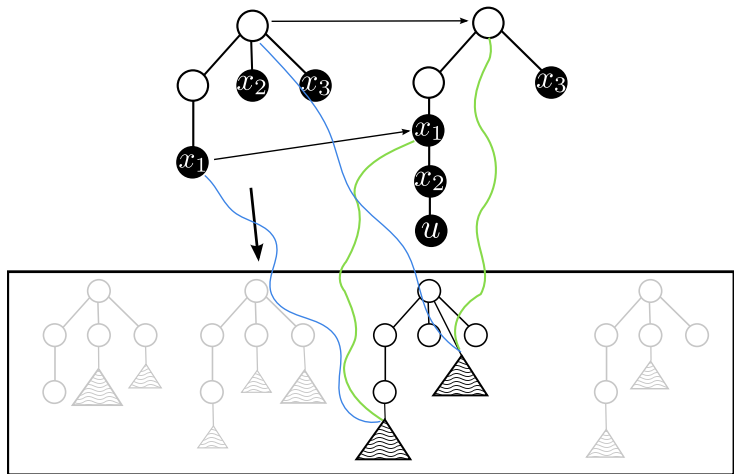
# Why should this work?



# Why should this work?



# Why should this work?



## Theorem

*Given a graph  $G$  with  $n$  nodes and a tree decomposition of  $G$  of width  $w$  the treedepth  $t$  of  $G$  can be decided in time  $2^{O(wt)} \cdot n$ .*



# Simple algorithm

- 1 Depth-first-search to construct treedepth decomposition  $T$ .
- 2 If depth greater than  $2^t - 1$  say NO.
- 3 Construct path decomposition  $\mathcal{P}$  from  $T$  of width  $2^t$ .
- 4 Run algorithm on  $\mathcal{P}$ .

## Theorem

*There is a (simple) algorithm to decide if a graph  $G$  with  $n$  nodes has treedepth  $t$  which runs in time  $2^{2^{O(t)}} \cdot n$ .*

# Fast algorithm

- 1 Use single exponential 5-approximation for treewidth<sup>1</sup>.
- 2 Remember  $\mathbf{tw}(G) \leq \mathbf{pw}(G) \leq \mathbf{td}(G) - 1$ .
- 3 If width is greater than  $5t$  say NO.
- 4 Else run algorithm on tree decomposition.

## Theorem

*There is a algorithm to decide if a graph  $G$  with  $n$  nodes has treedepth  $t$  which runs in time  $2^{O(t^2)} \cdot n$ .*

---

<sup>1</sup>Very useful result by Hans Bodlaender, Pål G. Drange, Markus S. Dregi, Fedor V. Fomin, Daniel Lokshtanov and Michał Pilipczuk

We have seen:

- An algorithm on tree decompositions which runs in time  $2^{O(wt)} \cdot n$ .
- A (relatively) simple direct algorithm in time  $2^{2^{O(t)}} \cdot n$ .
- A fast algorithm in time  $2^{O(t^2)} \cdot n$ .

## Related Questions

- Is it sensible to implement?
- Can we approximate treedepth in time  $2^{O(t)} \cdot n$ .
- Can we find new algorithms on treedepth which are better than working in the path decomposition given by a treedepth decomposition?

Thank you for listening.  
Questions?