

CHARACTERISING
STRUCTURAL
SPARSENESS
by
NEIGHBOURHOOD
COMPLEXITY

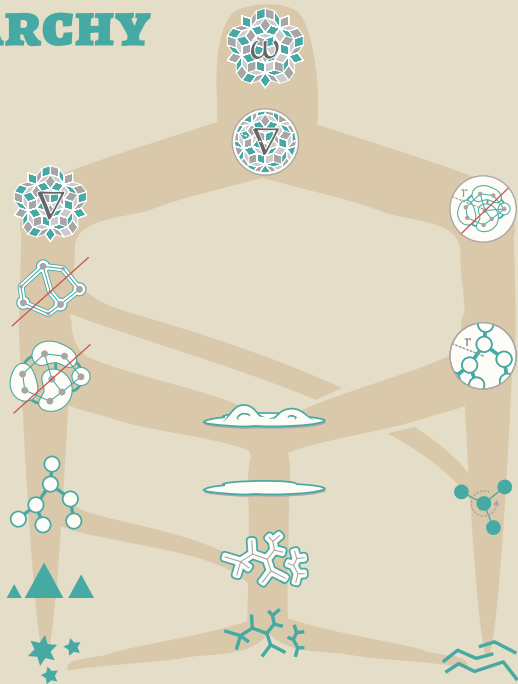
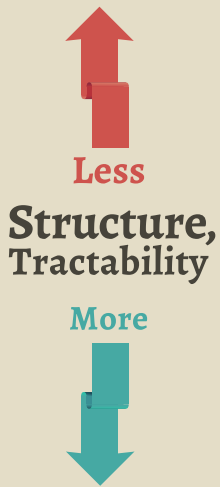
*Or: If your neighbourhood is boring,
you probably live in a sparse region.*

Felix Reidl
felix.reidl@gmail.com

Joint work with
Fernando Sánchez Villaamil
& **Konstantinos Stavropoulos**

Warwick '16

SPARSE HIERARCHY



GRAPH MEASURES

A *graph measure* is an isomorphism invariant function that maps graphs to \mathbb{R}^+ .

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- **Clique number** $\omega(G)$
- **Degeneracy** $\max_{H \subseteq G} \frac{2|E(H)|}{|V(H)|}$
- **Treewidth** $\text{tw}(G)$

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- Width measures**
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PARAMETRISED GRAPH MEASURES

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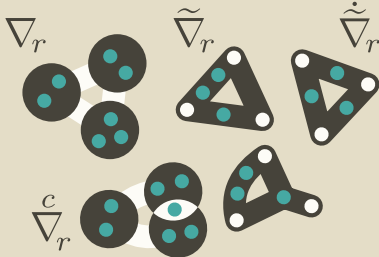
A graph class \mathcal{G} is f_r -bounded if there exists g s.t.

$$f_r(\mathcal{G}) = \sup_{G \in \mathcal{G}} f_r(G) \leq g(r) \quad \text{for all } r.$$

CHOOSE YOUR POISON



order-based



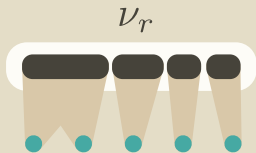
*shallow minor
flavours*



(d)tf-augm.



quasi-wideness



*neighbourhood
complexity*

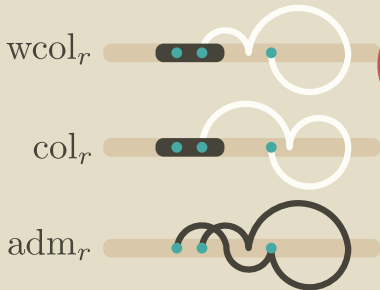


*low td/tw
colorings*

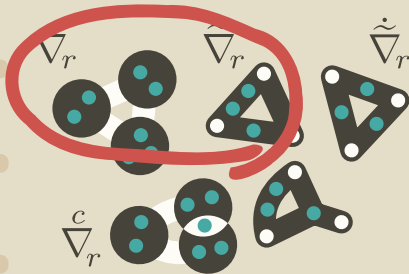


splitter games

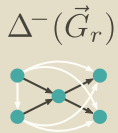
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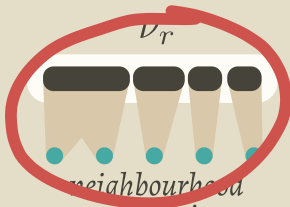
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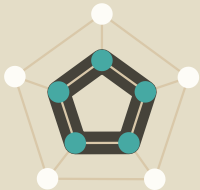
splitter games

CHARACTERISING STRUCTURAL SPARSENESS

SHALLOW ^{by} r -CENTRED
TOPOLOGICAL COLOURING
MINORS & NUMBERS

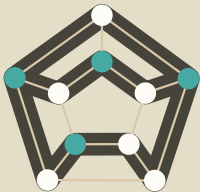
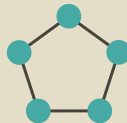


SUBSTRUCTURES



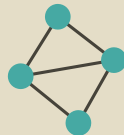
Select vertices, connect by
edges

SUBGRAPH



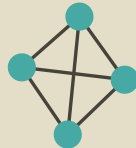
Select vertices, connect by
vertex-disjoint paths

TOP. MINOR



Select connected, disjoint
subgraphs, connect by edges

MINOR



FORBIDDEN SUBSTRUCTURES



H does not appear as a subgraph.



H does not appear as a topological minor.



H does not appear as a minor.

FORBIDDEN SUBSTRUCTURES



does not appear as a subgraph.
= **TRIANGLE-FREE GRAPHS**



does not appear as a
topological minor.
= **FORESTS**



does not appear as a minor.
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FORBIDDEN SUBSTRUCTURES



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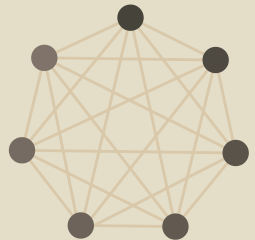
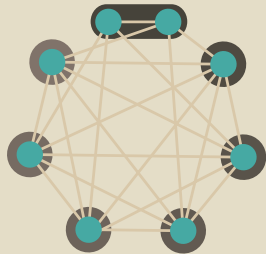
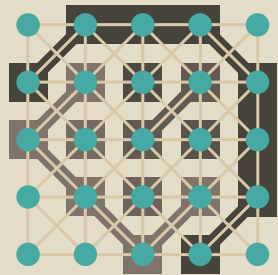


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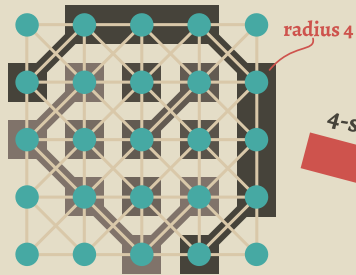


does not appear as a minor.
= **FORESTS**

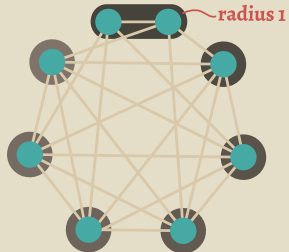
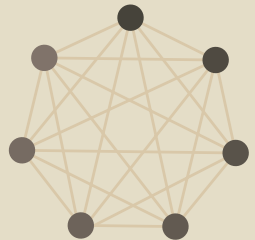
NOT ALL MINORS ARE EQUAL!



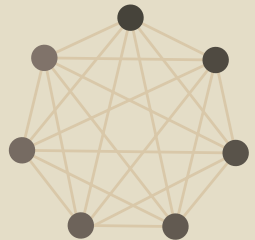
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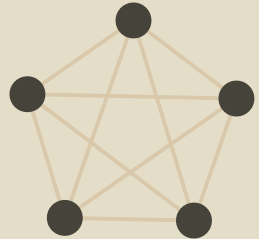
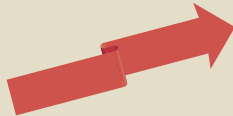
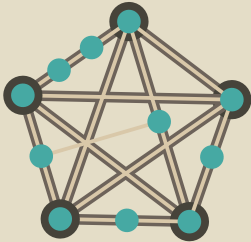
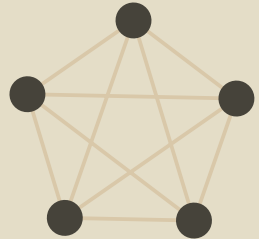
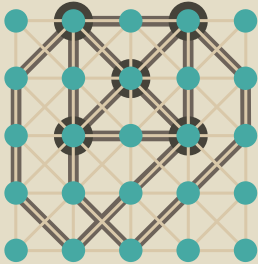
4-shallow minor



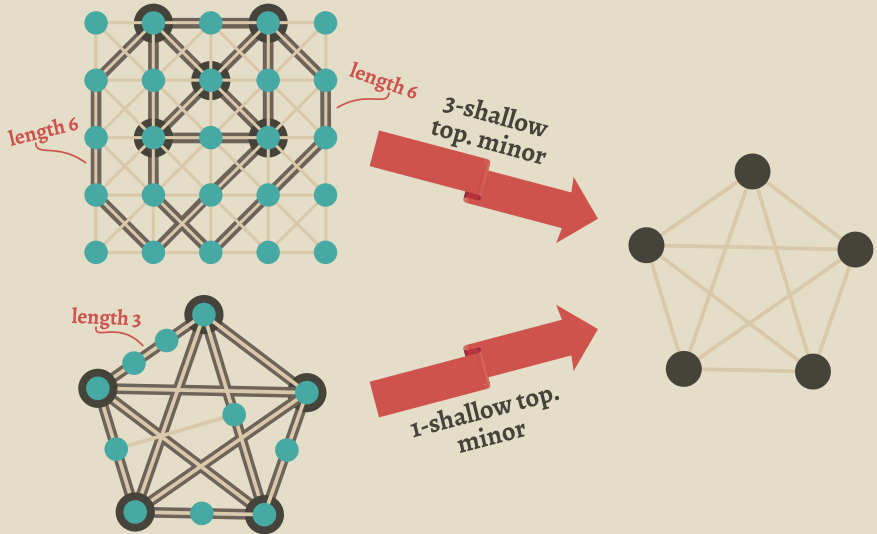
1-shallow minor



NOT ALL TOP. MINORS ARE EQUAL!



NOT ALL TOP. MINORS ARE EQUAL!



THE MAGIC FORMULA

GRAPH MEASURE + **DEPTH PARAMETRE** = **NOTION ^{of} STRUCTURAL SPARSENESS**

THE MAGIC FORMULA

**GRAPH
MEASURE**

+

**DEPTH
PARAMETRE**

=

**NOTION ^{of}
STRUCTURAL
SPARSENESS**

$$\frac{\|H\|}{|H|}$$

+

minor depth r

=

THE MAGIC FORMULA

GRAPH MEASURE + **DEPTH PARAMETRE** = **NOTION ^{of} STRUCTURAL SPARSENESS**

$$\frac{\|H\|}{|H|} + \text{minor depth } r = \nabla_r(G) = \max_{H \preceq_m^r G} \frac{\|H\|}{|H|}$$

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$$\tilde{\nabla}_r(G) \leq \nabla_r(G) \leq 4(4\tilde{\nabla}_r(G))^{(r+1)^2}$$

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$$\tilde{\nabla}_r(G) \asymp \nabla_r(G)$$

$$\log(\tilde{\nabla}_r(G)) = \Theta(\log(\nabla_r(G)))$$

Nešetřil & Ossona de Mendez

BOUNDED EXPANSION



A graph class \mathcal{G} has *bounded expansion* iff it is ∇_r -bounded.

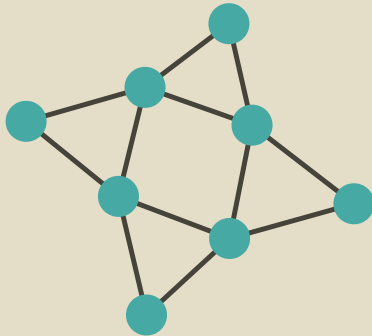


A graph class \mathcal{G} has *bounded expansion* iff it is $\tilde{\nabla}_r$ -bounded.

“We allow dense minors in our graph, but only on a large scale”

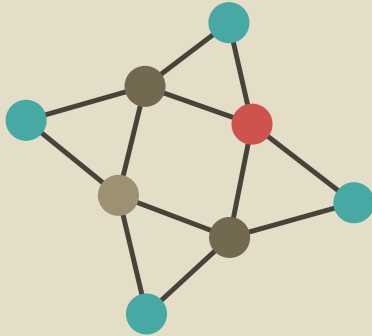
CENTRED COLOURINGS

A vertex colouring is *centred* if every connected subgraph contains a unique colour, a *centre*.



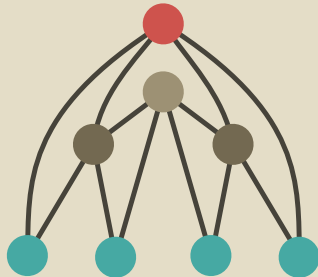
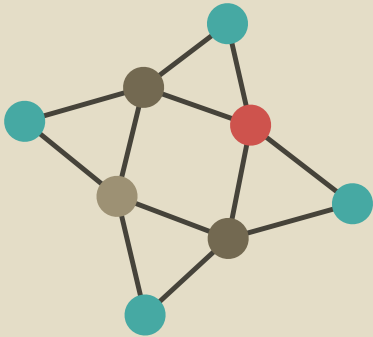
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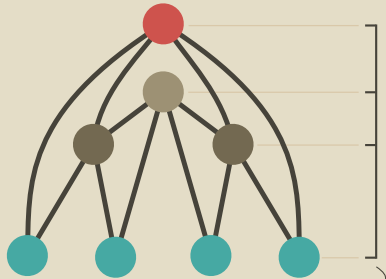
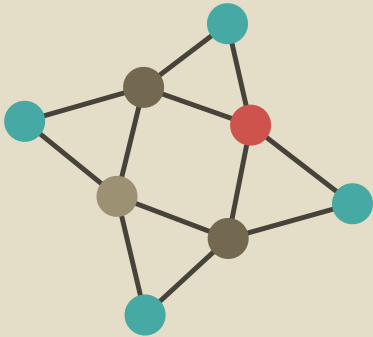
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$$tw(G) + 1 \leq pw(G) + 1 \leq td(G)$$

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$\text{td}(H)$ + ? = ?

THE MAGIC FORMULA

GRAPH MEASURE + **DEPTH PARAMETRE** = **NOTION ^{of} STRUCTURAL SPARSENESS**

$\text{td}(H)$ + colour subsets of size r = ?

A vertex colouring is r -centred if every connected subgraph either

- contains a centre, or
- contains r or more colours.

THE MAGIC FORMULA

GRAPH MEASURE + **DEPTH PARAMETRE** = **NOTION^{of} STRUCTURAL SPARSENESS**

$$\text{td}(H) + \text{colour subsets of size } r = \chi_r(G)$$

Minimum number of colours needed for an r -centred colouring of G

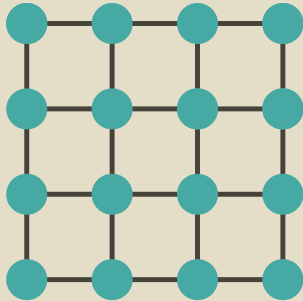
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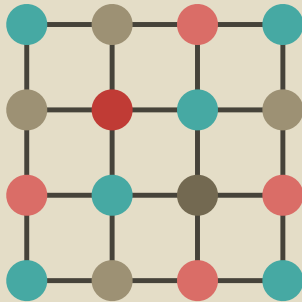
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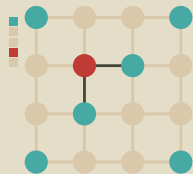
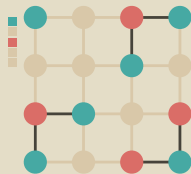
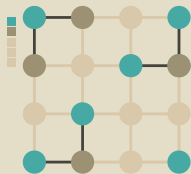
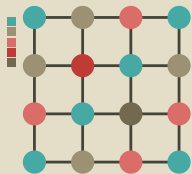
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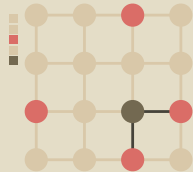
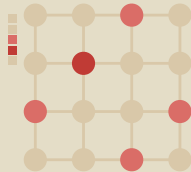
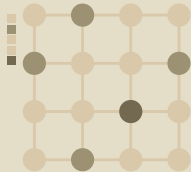
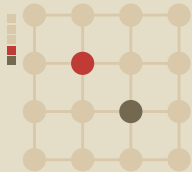
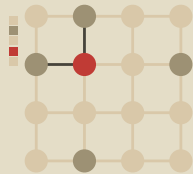
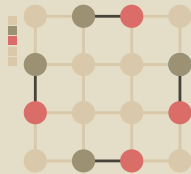
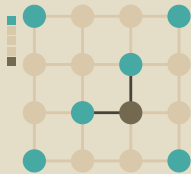
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r -CENTRED COLOURINGS



$r = 3$



BOUNDED EXPANSION (AGAIN)

$$\chi_r(G) \asymp \tilde{\nabla}_r(G)$$

Nešetřil & Ossona de Mendez



A graph class \mathcal{G} has bounded expansion iff it is χ_r -bounded.

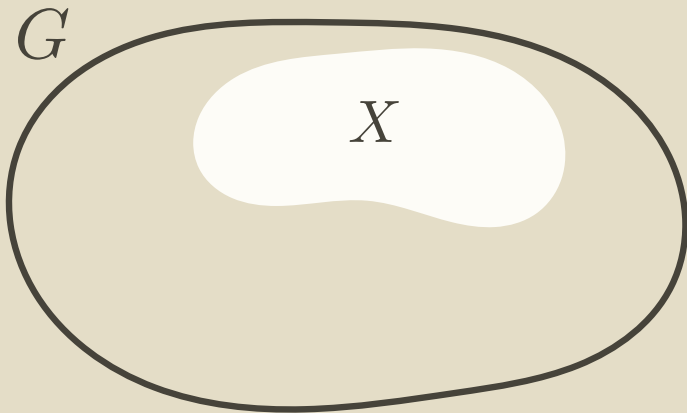
“Structurally sparse graphs can be decomposed locally into parts of bounded width”

Interlude

~~CUT~~ COMPLEXITY

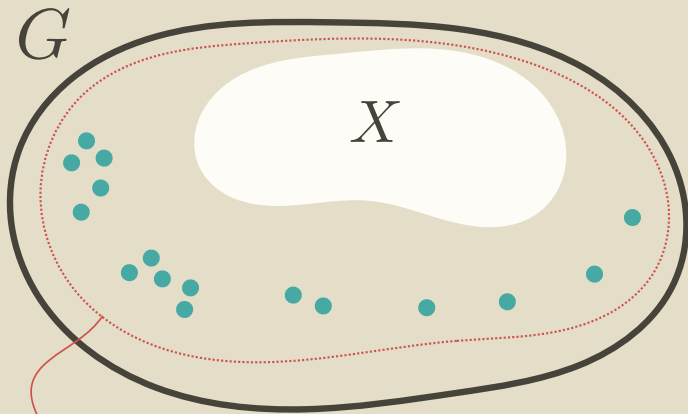
BOUNDED CUT COMPLEXITY

(Works in many sparse classes)



BOUNDED CUT COMPLEXITY

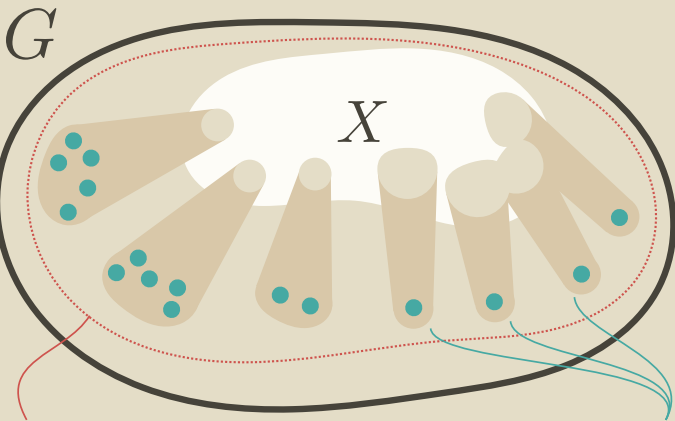
(Works in many sparse classes)



$N(X)$ is large...

BOUNDED CUT COMPLEXITY

(Works in many sparse classes)



$N(X)$ is large...

...but $N(X)/N_X$
has size $O(|X|)$

CUT COMPLEXITY AS A MEASURE

$$\xi(G) = \max_{X \subseteq V(G)} \frac{|\{N(v) \cap X\}_{v \in G}|}{|X|}$$

Alternatively $N[v]$

Alternatively $v \in G \setminus X$

Normalise to make subsets comparable

CUT COMPLEXITY AS A MEASURE

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Normalise to make subsets comparable

GRAPH MEASURE + **DEPTH PARAMETRE** = etc. etc.

FROM CUTS TO NEIGHBOURHOODS

$$\xi(G) = \max_{X \subseteq V(G)} \frac{|\{N(v) \cap X\}_{v \in G}|}{|X|}$$

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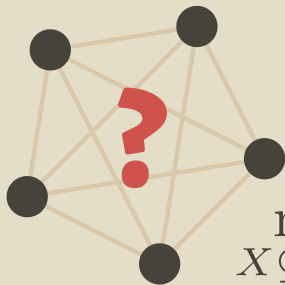
DEPTH



$$\max_{X \subseteq V(G)} \frac{|\{N^r[v] \cap X\}_{v \in G}|}{|X|}$$

FROM CUTS TO NEIGHBOURHOODS

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$$\max_{X \subseteq V(G)}$$

DEPTH

$$\frac{|\{N^r[v] \cap X\}_{v \in G}|}{|X|}$$

FROM CUTS TO NEIGHBOURHOODS

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DEPTH



$$\max_{X \subseteq V(G)} \frac{|\{N(v) \cap X\}_{v \in G}|}{|X|}$$

DENSE GRAPHS 

FROM CUTS TO NEIGHBOURHOODS

$$\xi(G) = \max_{X \subseteq V(G)} \frac{|\{N(v) \cap X\}_{v \in G}|}{|X|}$$

**CONSIDER ALL
SUBGRAPHS**



$$\nu_r(G) = \max_{\substack{H \subseteq G, \\ X \subseteq V(H)}} \frac{|\{N^r[v] \cap X\}_{v \in H}|}{|X|}$$

DEPTH



$$\frac{|\{N^r[v] \cap X\}_{v \in H}|}{|X|}$$

FROM CUTS TO NEIGHBOURHOODS

$$\xi(G) = \max_{X \subseteq V(G)} \frac{|\{N(v) \cap X\}_{v \in G}|}{|X|}$$

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*“Neighbourhood
Complexity”*



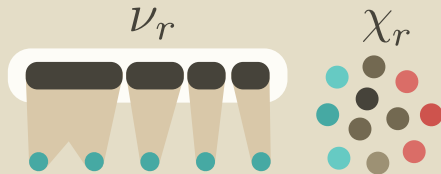
CHARACTERISING STRUCTURAL SPARSENESS

by

NEIGHBOURHOOD COMPLEXITY

Part I

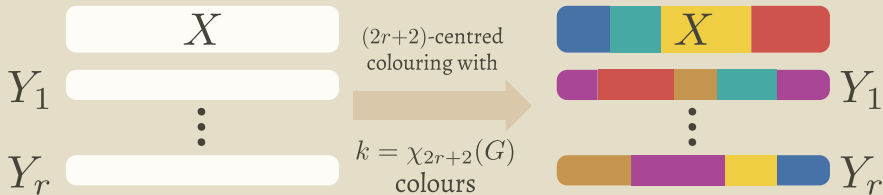
The story of $\nu_r(G) \leq f(\chi_{2r+2}(G))$



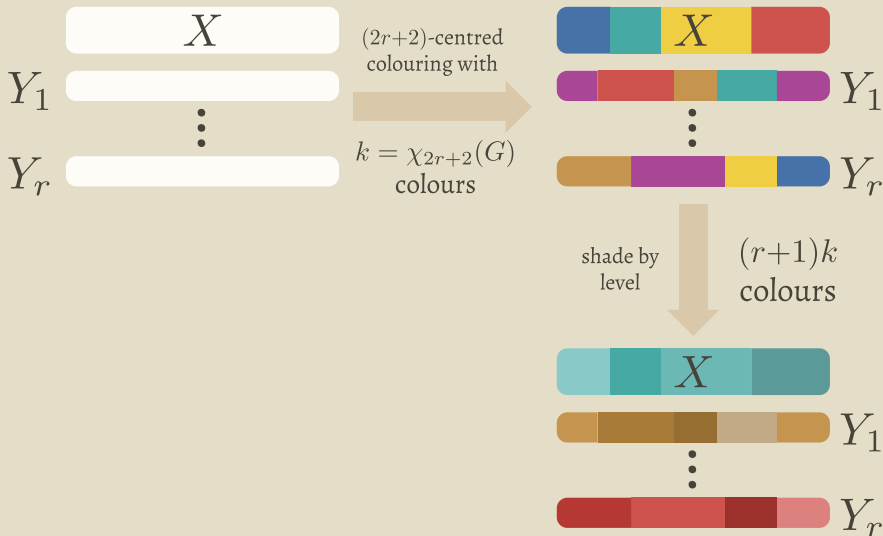
BOUNDING N.C. BY CENTRED COLS.

$$\begin{array}{c} \\ Y_1 \\ \\ Y_r \end{array} \begin{array}{c} \boxed{X} \\ \boxed{\vdots} \\ \boxed{} \end{array}$$

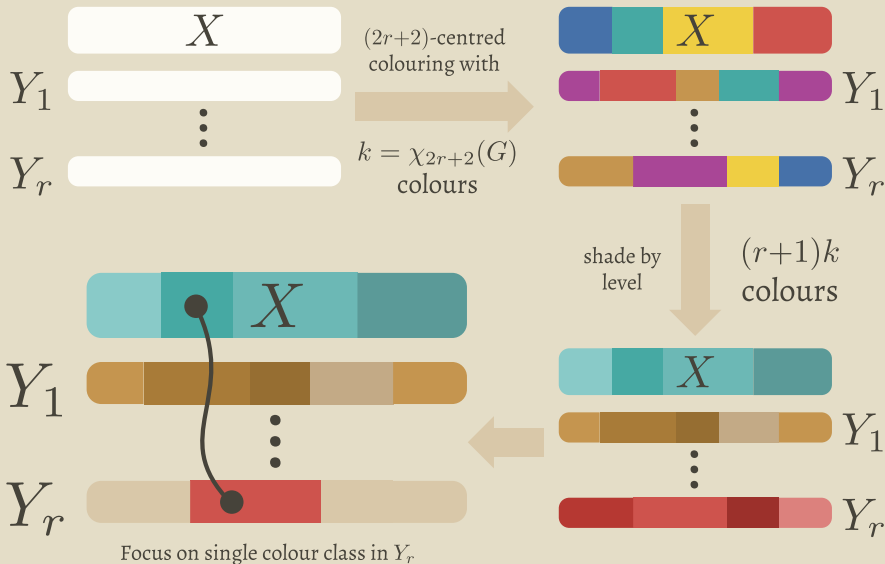
BOUNDING N.C. BY CENTRED COLS.



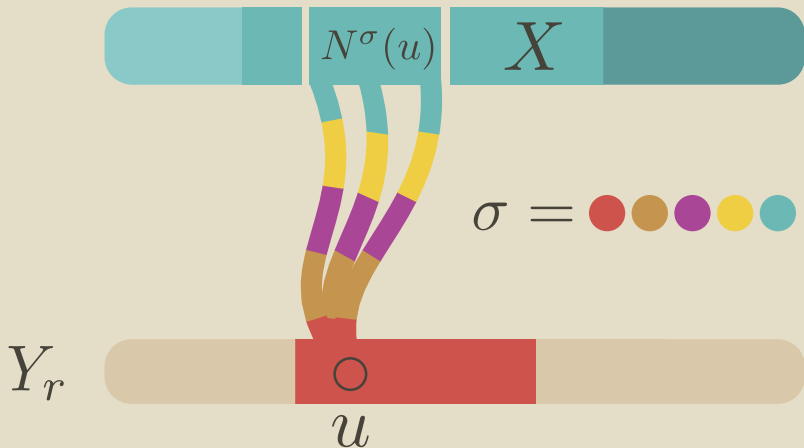
BOUNDING N.C. BY CENTRED COLS.



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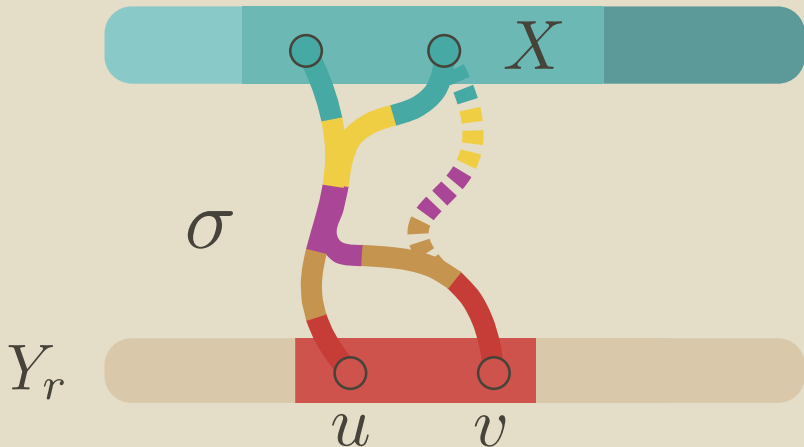


SIGNATURES & NEIGHBOURHOODS



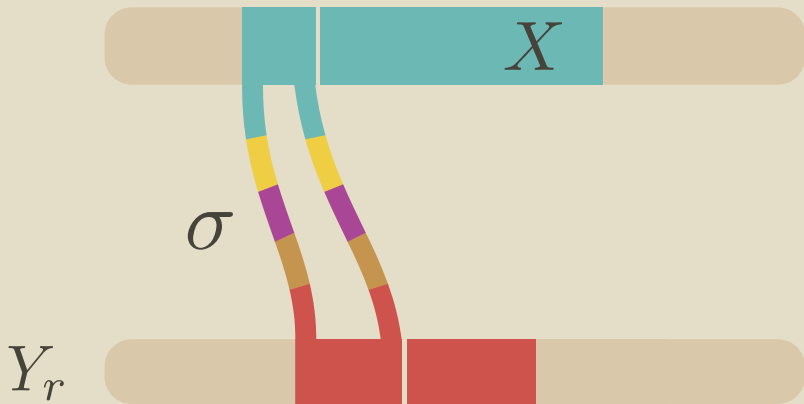
$$N^r(u) \cap X = \bigcup_{\sigma} N^\sigma(u)$$

SIGNATURES: OBSERVATION I



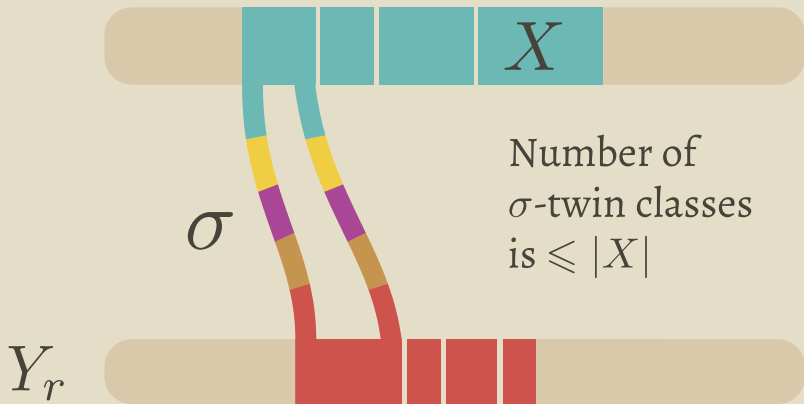
For a fixed signature σ and $u, v \in Y_r$, either $N^\sigma(u) = N^\sigma(v)$ or $N^\sigma(u) \cap N^\sigma(v) = \emptyset$.

SIGNATURES: OBSERVATION I



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SIGNATURES: OBSERVATION I



For a fixed signature σ and $u, v \in Y_r$, either $N^\sigma(u) = N^\sigma(v)$ or $N^\sigma(u) \cap N^\sigma(v) = \emptyset$.

SIGNATURES: OBSERVATION II



Y_r/σ_1



Y_r/σ_2



SIGNATURES: OBSERVATION II



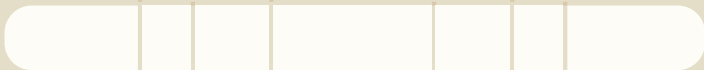
Y_r/σ_1



Y_r/σ_2



$Y_r/(\sigma_1, \sigma_2)$



SIGNATURES: OBSERVATION II



This would be bad:
 $\approx 2^{|X|}$ neighbourhood classes



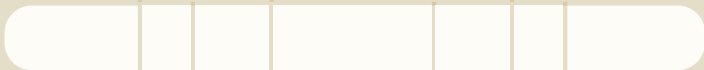
SIGNATURES: OBSERVATION II



This would be bad:
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$Y_r/(\sigma_1, \sigma_2)$



SIGNATURES: OBSERVATION II



Y_r/σ_1



u

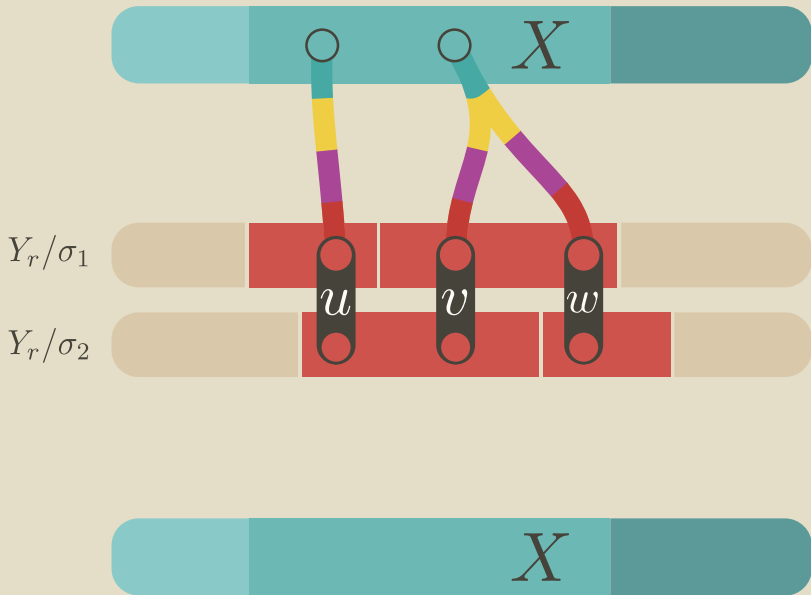
v

w

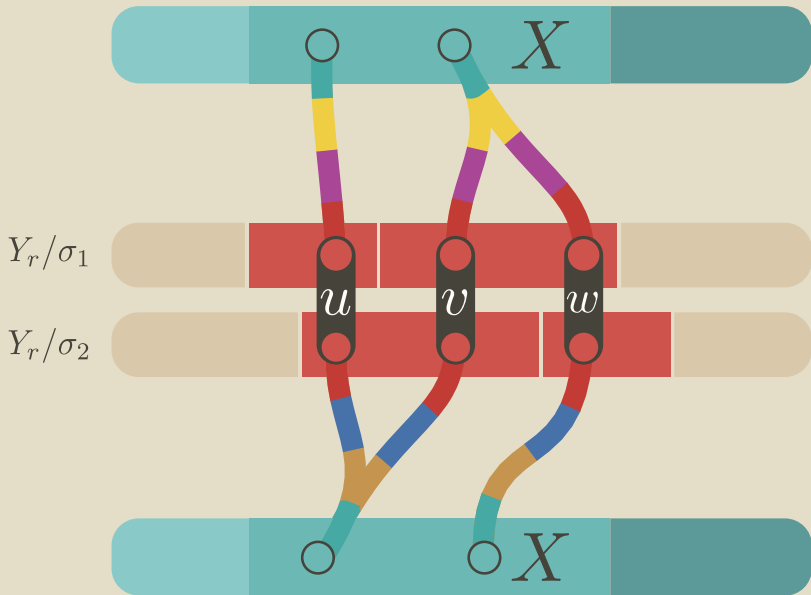
Y_r/σ_2



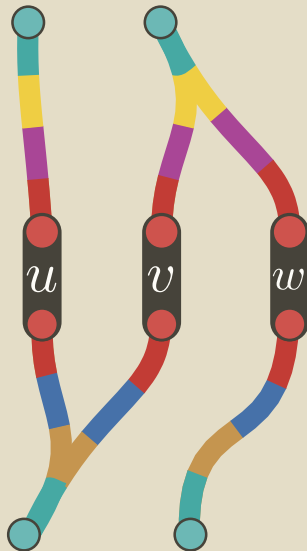
SIGNATURES: OBSERVATION II



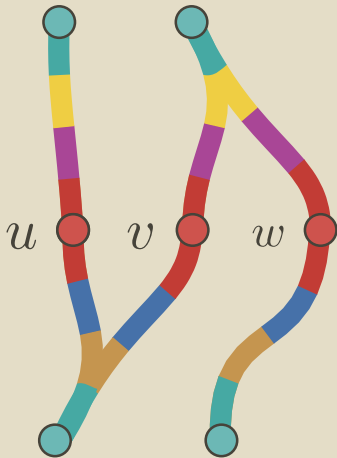
SIGNATURES: OBSERVATION II



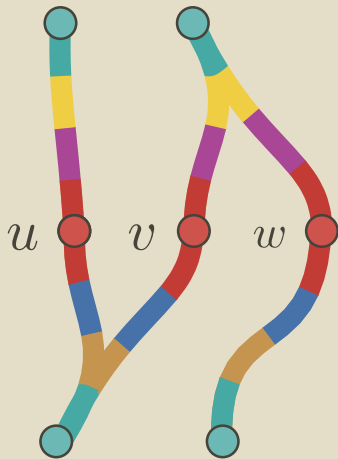
SIGNATURES: OBSERVATION II



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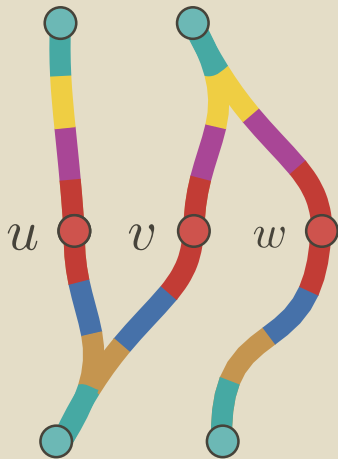


SIGNATURES: OBSERVATION II



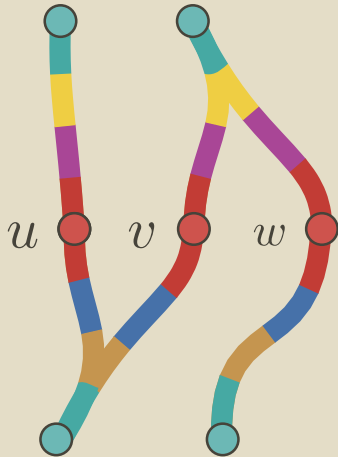
- **Connected** subgraph

SIGNATURES: OBSERVATION II



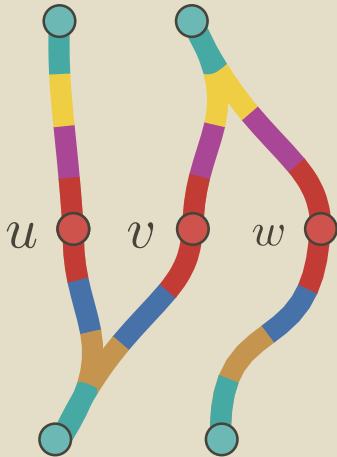
- **Connected** subgraph
- At most $2r + 1$ colours

SIGNATURES: OBSERVATION II



- **Connected** subgraph
- At most $2r + 1$ colours
- Every colour appears at least **twice**

SIGNATURES: OBSERVATION II



- **Connected** subgraph
- At most $2r + 1$ colours
- Every colour appears at least **twice**

This subgraph has few colours and no centre!

Contradiction!

SIGNATURES: OBSERVATION II

For every σ_1 -twin class $C_1 \subseteq Y_r$ and σ_2 -twin class $C_2 \subseteq Y_r$ we have that either $C_1 \subseteq C_2$, $C_2 \subseteq C_1$ or $C_1 \cap C_2 = \emptyset$.

Y_r/σ_1



Y_r/σ_2



SIGNATURES: OBSERVATION II

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Y_r/σ_1



Y_r/σ_2



Y_r/σ_3

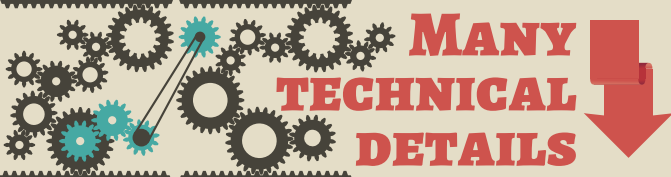


The number of twin-classes in Y_r is at most $f(\chi_{2r+2}(G))|X|$.

SIGNATURES: OBSERVATION II

For every σ_1 -twin class $C_1 \subseteq Y_r$ and σ_2 -twin class $C_2 \subseteq Y_r$ we have that either $C_1 \subseteq C_2$, $C_2 \subseteq C_1$ or $C_1 \cap C_2 = \emptyset$.

The number of twin-classes in Y_r is at most $f(\chi_{2r+2}(G))|X|$.



**MANY
TECHNICAL
DETAILS**

$$\nu_r(G) \leq f(\chi_{2r+2}(G))$$

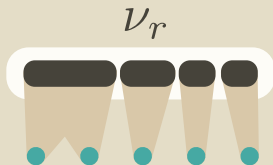
CHARACTERISING STRUCTURAL SPARSENESS

by

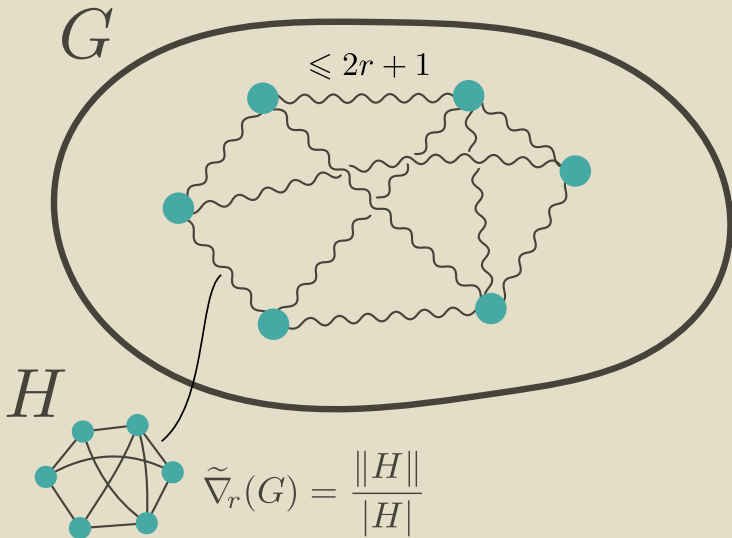
NEIGHBOURHOOD COMPLEXITY

Part II

The (shorter) story of
 $\tilde{\nabla}_{r-1}(G) \leq f(\nu_{\leq r}(G))$



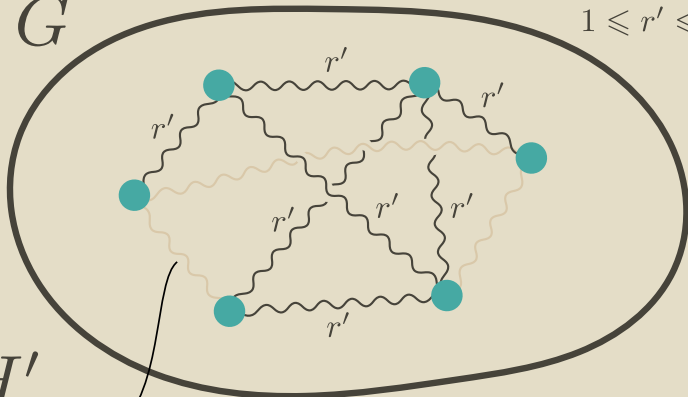
DENSE TOP. MINORS = HIGH COMPLEXITY



DENSE TOP. MINORS = HIGH COMPLEXITY

G

$$1 \leq r' \leq 2r + 1$$



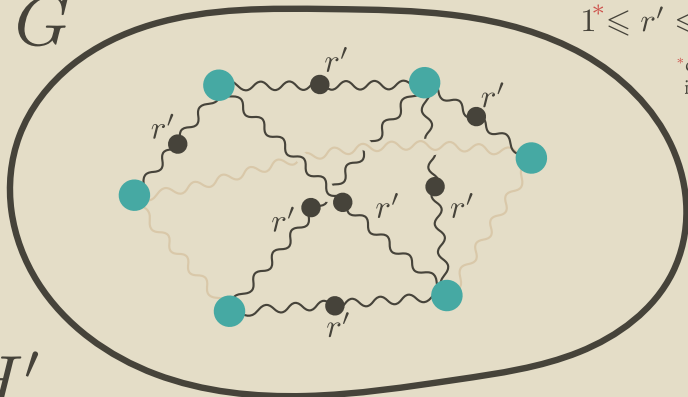
H'



$$\tilde{\nabla}_r(G) \leq (2r+1) \frac{\|H'\|}{|H'|}$$

DENSE TOP. MINORS = HIGH COMPLEXITY

G



$$1^* \leq r' \leq 2r + 1$$

*case $r' = 1$
is more involved

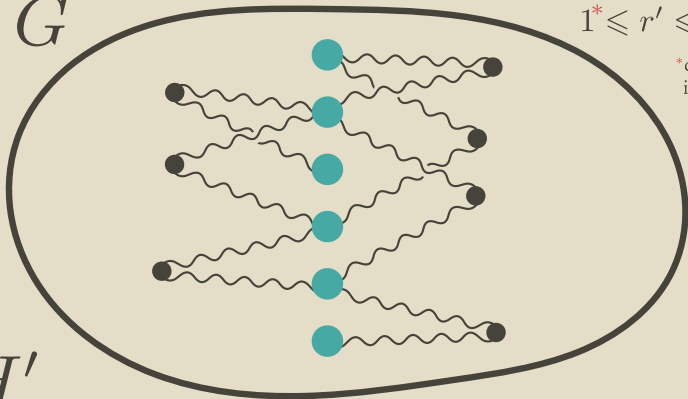
H'



$$\tilde{\nabla}_r(G) \leq (2r+1) \frac{\|H'\|}{|H'|}$$

DENSE TOP. MINORS = HIGH COMPLEXITY

G



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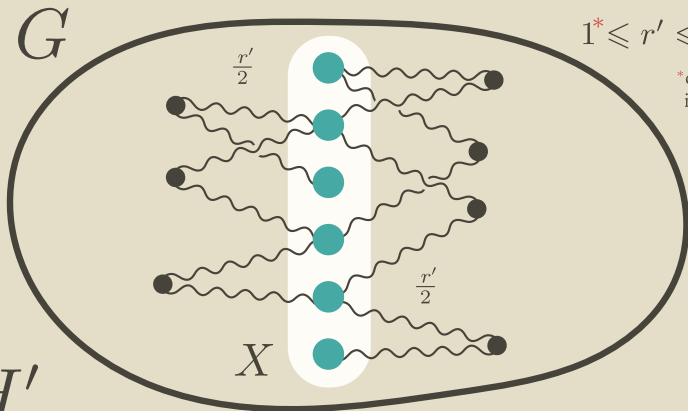
H'



$$\tilde{\nabla}_r(G) \leq (2r+1) \frac{\|H'\|}{|H'|}$$

DENSE TOP. MINORS = HIGH COMPLEXITY

G



$$1^* \leq r' \leq 2r + 1$$

*case $r' = 1$
is more involved

H'



$$\tilde{\nabla}_r(G) \leq (2r+1) \frac{\|H'\|}{|H'|} \leq (2r+1) \nu_{\leq r+1}(G)$$

BOUNDED EXPANSION (AGAIN)

$$f_1(\tilde{\nabla}_{r-1}(G)) \leq \nu_{\leq r}(G) \leq f_2(\chi_{2r+2}(G))$$

R., Sánchez Villaamil, Stavropoulos



A graph class \mathcal{G} has bounded expansion iff it is ν_r -bounded.

“Structurally sparse graphs have simple neighbourhood structures”

*Summary
& Future work*



SUMMARY

**GRAPH
MEASURE**

+

**DEPTH
PARAMETRE**

=

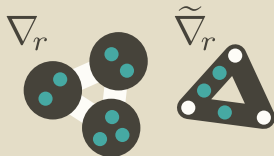
**NOTION ^{of}
STRUCTURAL
SPARSENESS**

$$\frac{\|H\|}{|H|}$$

+

topological
minor depth r

=



$$\text{td}(H)$$

+

colour subsets
of size r

=



cut
complexity

+

neighbourhood
radius r

=



\mathcal{V}_r



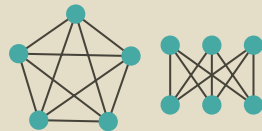
FUTURE WORK



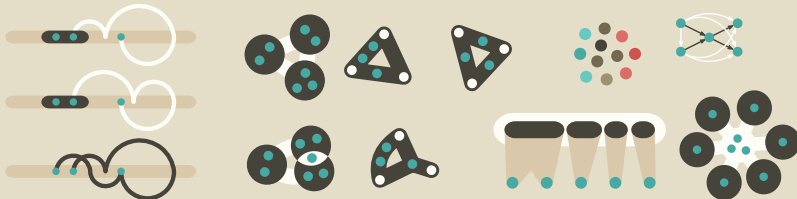
Characterise nowhere dense classes by neighbourhood complexity? **Need polynomial bound!**



What about dense classes?
Neighbourhood complexity without taking subgraphs...



Find more characterisations!



THANKS!

Questions?



References

Nešetřil, J., & de Mendez, P. O. (2012).

Sparsity: graphs, structures, and algorithms (Vol. 28).
Springer Science & Business Media.

FR. (2015). **Structural sparseness and complex networks.**

FR, Sánchez Villaamil, F., & Stavropoulos, K. (2016).

Characterising Bounded Expansion by Neighbourhood Complexity.
arXiv preprint arXiv:1603.09532.