

Linear kernels for graphs excluding a topological minor

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Reduction via protrusions

(Topological) Minors

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Linear kernels in sparse graphs

Overview

- Framework for planar graphs

Guo and Niedermeier: *Linear problem kernels for NP-hard problems on planar graphs*

- Meta-result for graphs of bounded genus

Bodlaender, Fomin, Lokshtanov, Penninkx, Saurabh and Thilikos: *(Meta) Kernelization*

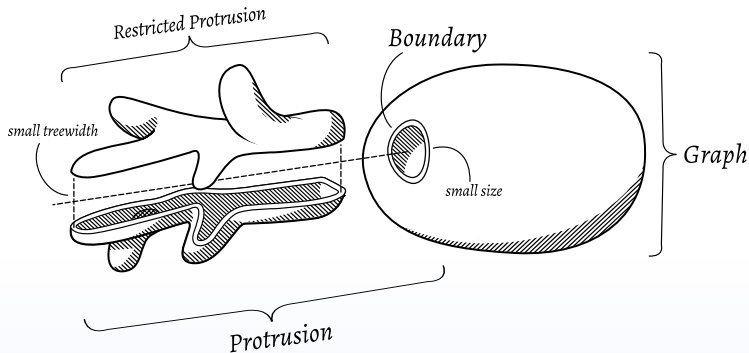
- Meta-result for graphs excluding a fixed graph as a minor

Fomin, Lokshtanov, Saurabh and Thilikos: *Bidimensionality and kernels*

- *Our contribution*: general result for graphs excluding a fixed graph as a *topological* minor

Reduction via protrusions

Protrusion anatomy



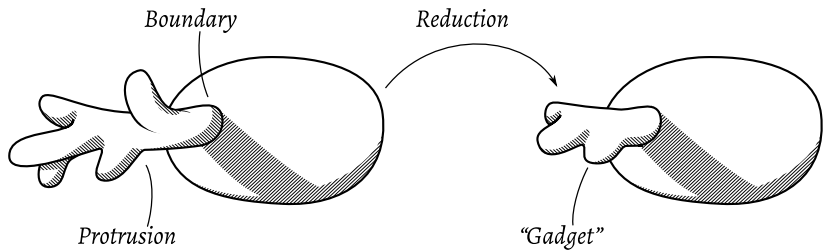
Definition

$X \subseteq V(G)$ is a t -protrusion if

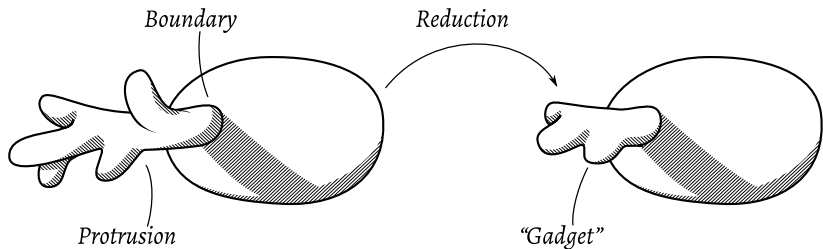
- 1 $|\partial(X)| = |N(X) \setminus X| \leq t$
- 2 $\mathbf{tw}(G[X]) \leq t$

(small boundary)

(small treewidth)

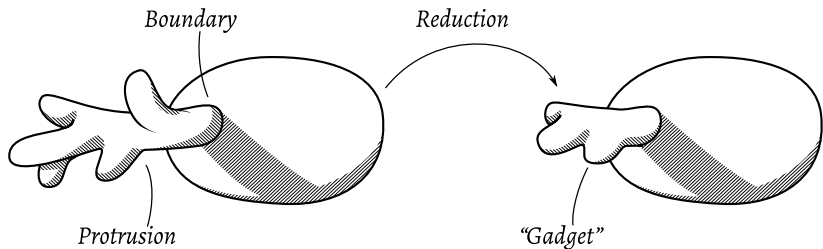


We want to replace a large protrusion by something smaller.
Requires that the problem...



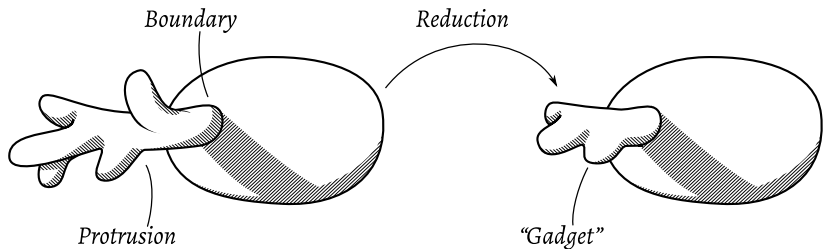
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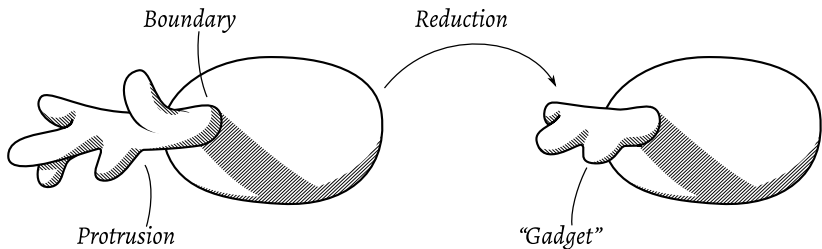
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- 2 ...admits small gadgets (finite integer index)



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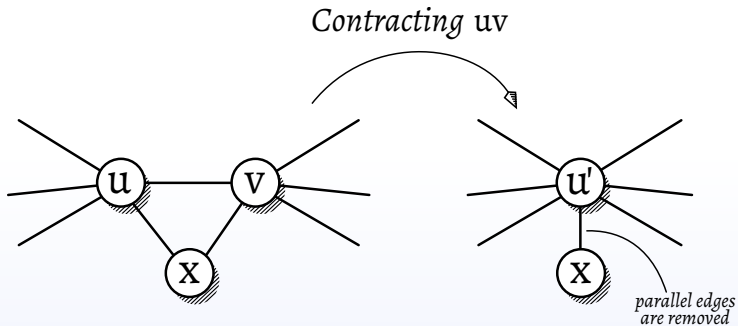
- 1 ...can be solved by dynamic programming on graphs of bounded treewidth
- 2 ...admits small gadgets (*finite integer index*)

Note: the reduction can decrease the parameter.

This is the only reduction.

(Topological) Minors

Edge contraction



Graph relations

(now with contractions!)

Graph relations

(now with contractions!)

Relation

Operations

induced subgraph

delete vertices

subgraph

topological minor

minor

Graph relations

(now with contractions!)

Relation

Operations

induced subgraph

delete vertices

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delete vertices and edges

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delete vertices and edges,
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Graph relations

(now with contractions!)

Relation

Operations

induced subgraph

delete vertices

subgraph

delete vertices and edges

topological minor

delete vertices and edges,
contract edges *incident to a
degree-2 vertex*

minor

delete vertices and edges,
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Properties of H-topological-minor-free graphs

Let G be a graph excluding H as a topological minor.

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- Not interested in structure of H , but its size $r = |H|$

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① $m \leq \frac{1}{2}\beta r^2 n$

(for some $\beta < 10$)

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- ① $m \leq \frac{1}{2}\beta r^2 n$ (for some $\beta < 10$)
- ② #cliques $\leq 2^{\tau r \log r} n$ (for some $\tau < 4.51$)
- ③ Closed under taking topological minors

Our result and how it works

Requirements

(besides the ones mentioned before)

Definition (Treewidth bounding)

A parameterized graph problem Π is called *treewidth bounding* if for every $(G, k) \in \Pi$ it holds that there exists a set $S \subseteq V(G)$ such that

- 1 $|S| \leq ck$
- 2 $\text{tw}(G - S) \leq t$

for constants c, t only depending on Π .

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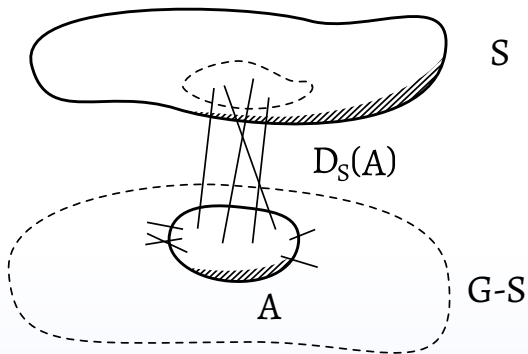
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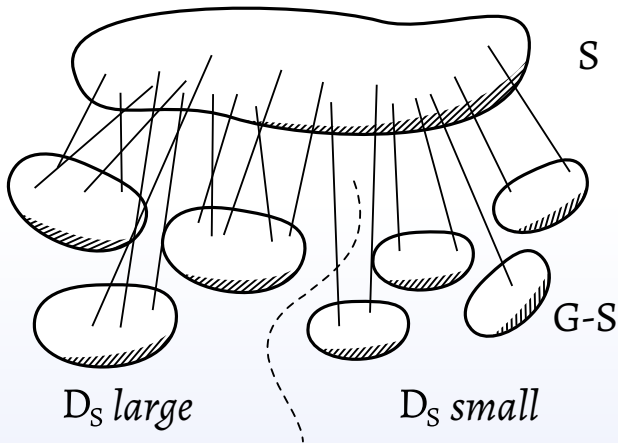
- S usually is the solution set
- VERTEX COVER, FEEDBACK VERTEX SET in general graphs
- CHORDAL VERTEX DELETION in graphs with bounded clique-size

A little bit of notation

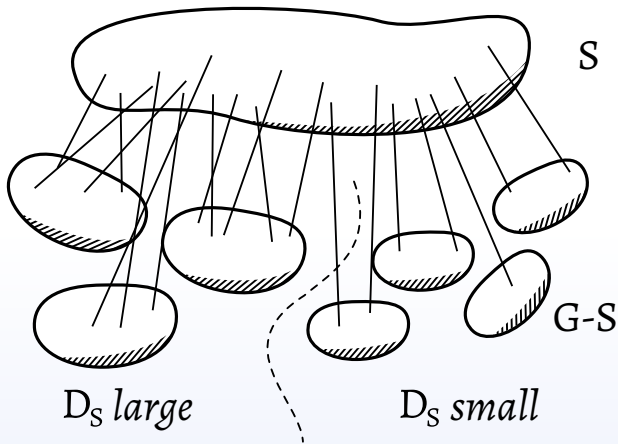


We write $D_S(A) = |\{u \in S \mid v \in A : uv \in E(G)\}|$ for the number of vertices in S that have neighbours in A (for disjoint sets S, A)

A decomposition

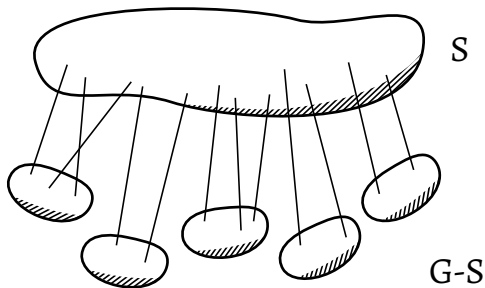


A decomposition



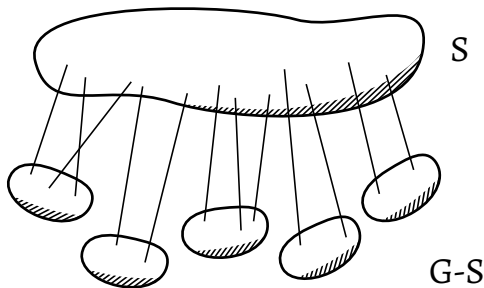
Reduced instance: large protrusions are gone

Small-degree components



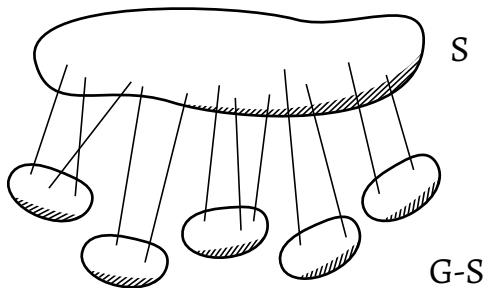
- $D_S(C) < r$, therefore boundary of size r

Small-degree components



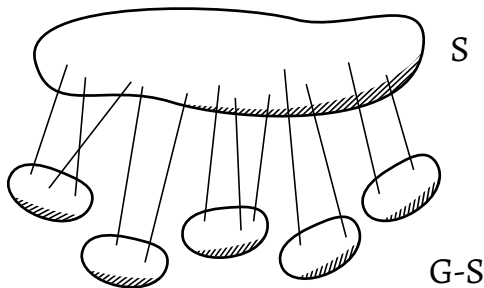
- $D_S(C) < r$, therefore boundary of size r
- C has constant treewidth (problem is treewidth bounding)

Small-degree components



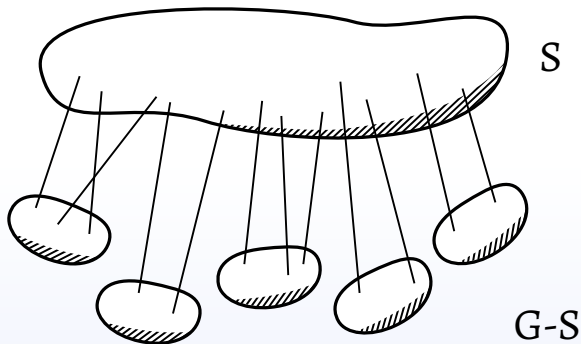
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Small-degree components

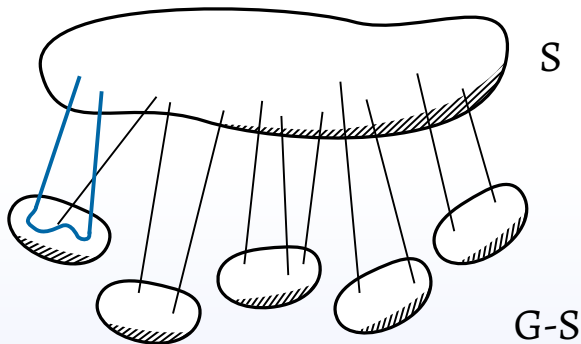


- $D_S(C) < r$, therefore boundary of size r
 - C has constant treewidth (problem is treewidth bounding)
- ⇒ Each small-degree component has constant size (reduced instance)
- What about the *number* of small-degree components?

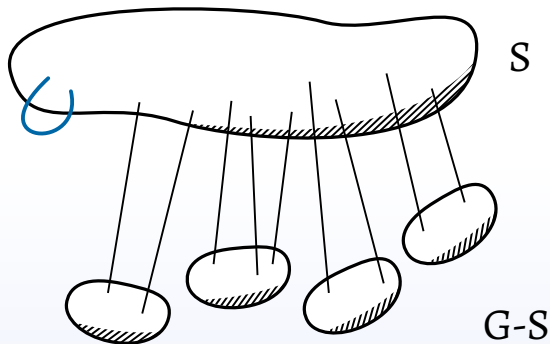
Small-degree components



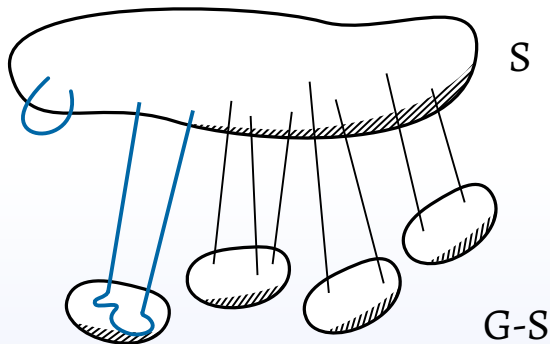
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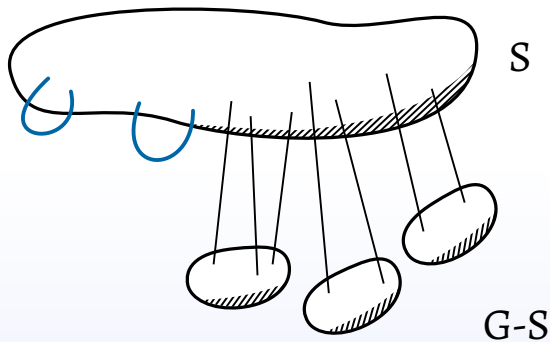
Small-degree components



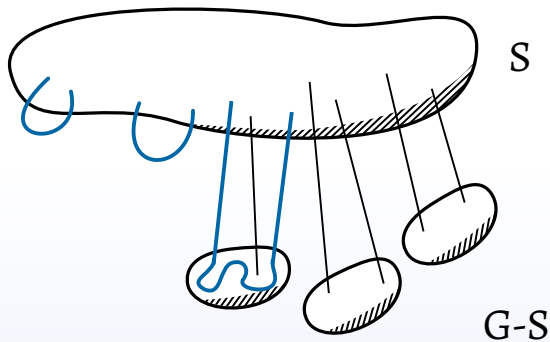
Small-degree components



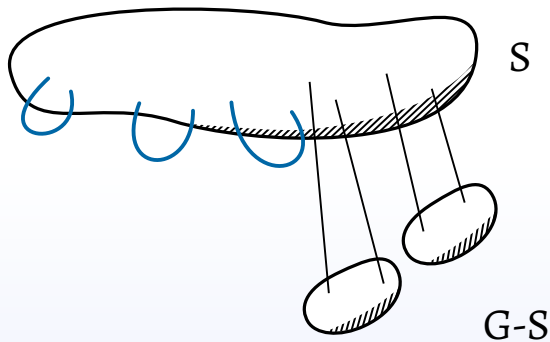
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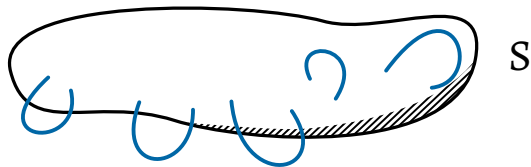
Small-degree components



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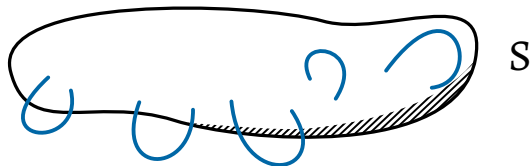


Small-degree components



$G-S$

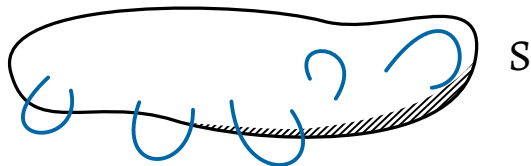
Small-degree components



$G-S$

- How often can we do this?

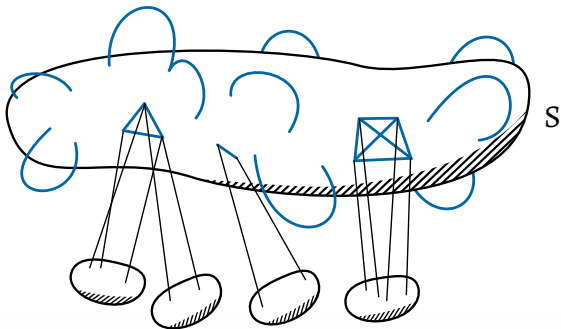
Small-degree components



G-S

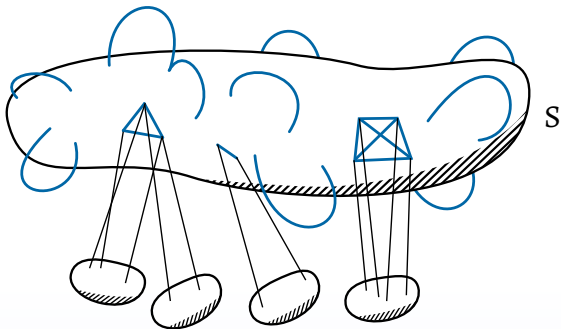
- How often can we do this?
- Is it exhaustive?

Small-degree components



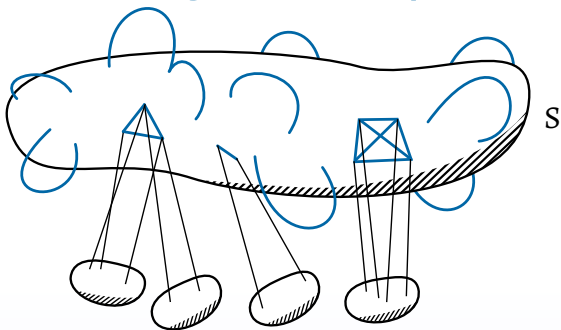
- Components now connected to cliques (or not finished)

Small-degree components



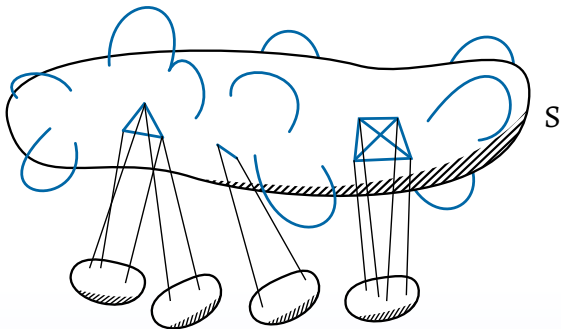
- Components now connected to cliques (or not finished)
- $G[S]$ is H -topological minor free, therefore...

Small-degree components



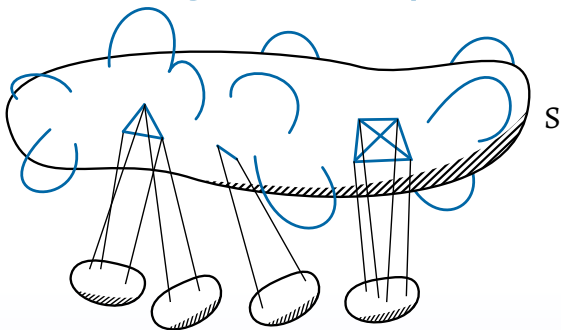
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 - ... $O(|S|) = O(k)$ edges

Small-degree components



- Components now connected to cliques (or not finished)
- $G[S]$ is H -topological minor free, therefore...
 - ... $O(|S|) = O(k)$ cliques
 - ... $O(|S|) = O(k)$ edges
- Constant number of vertices in components connected to a common clique (or large protrusion in G)

50% done!
(not)

$O(k)$ vertices in small-degree
components

Large-degree components

Very technical. Two ingredients:

Large-degree components

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- 1 At most $O(k)$ connected *subgraphs* with $D_S \geq r$

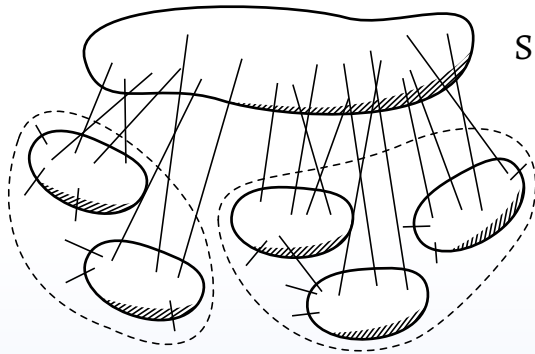
Large-degree components

Very technical. Two ingredients:

- ① At most $O(k)$ connected *subgraphs* with $D_S \geq r$
- ② Tree-decomposition allows us to find many such subgraphs *of constant size*

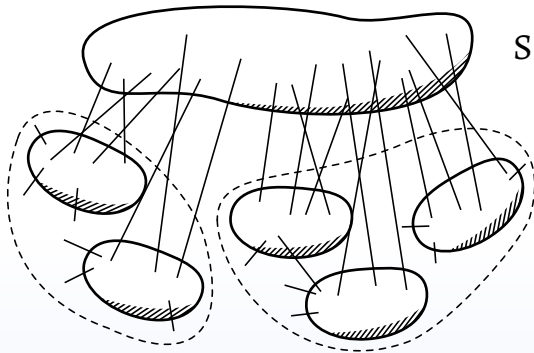
Large-degree components

Ingredient one



Large-degree components

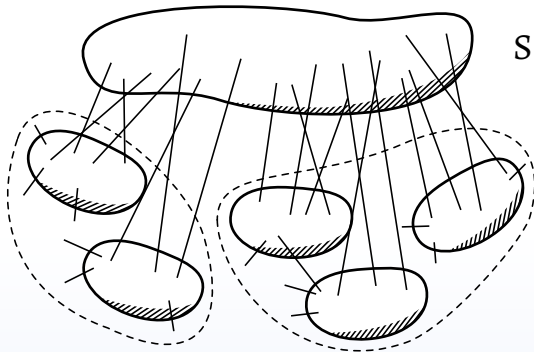
Ingredient one



- Same idea as before: contract connected subgraphs into edges in S

Large-degree components

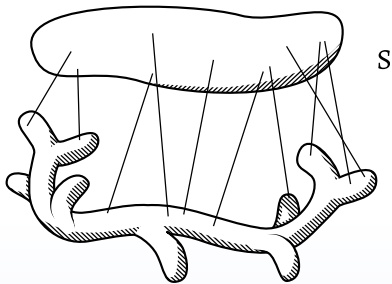
Ingredient one



- Same idea as before: contract connected subgraphs into edges in S
- Exhaustive, else K_r as a subgraph in S and thus H as a topological minor in G

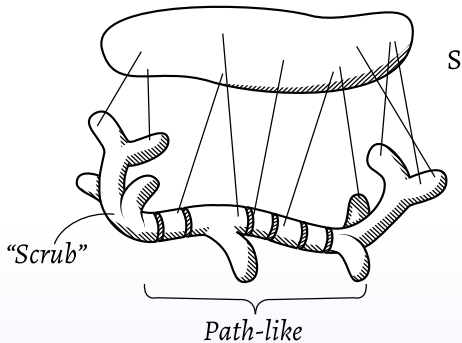
Large-degree components

Ingredient two



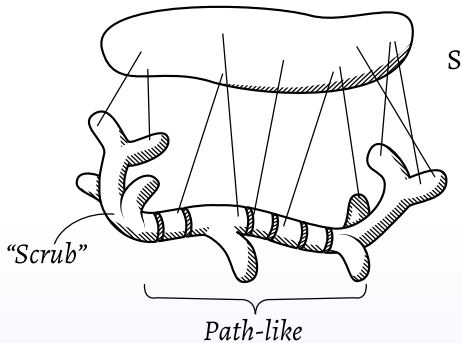
Large-degree components

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Large-degree components

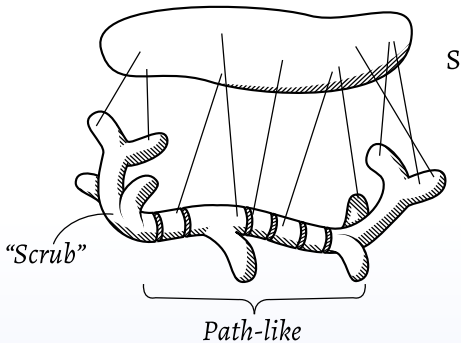
Ingredient two



- Walk along path-decomposition

Large-degree components

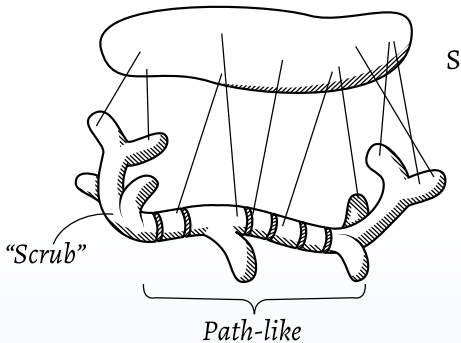
Ingredient two



- Walk along path-decomposition
- Small degree \Rightarrow Small boundary

Large-degree components

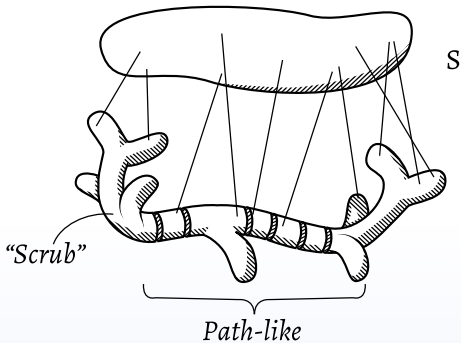
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Large-degree components

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Conclusion

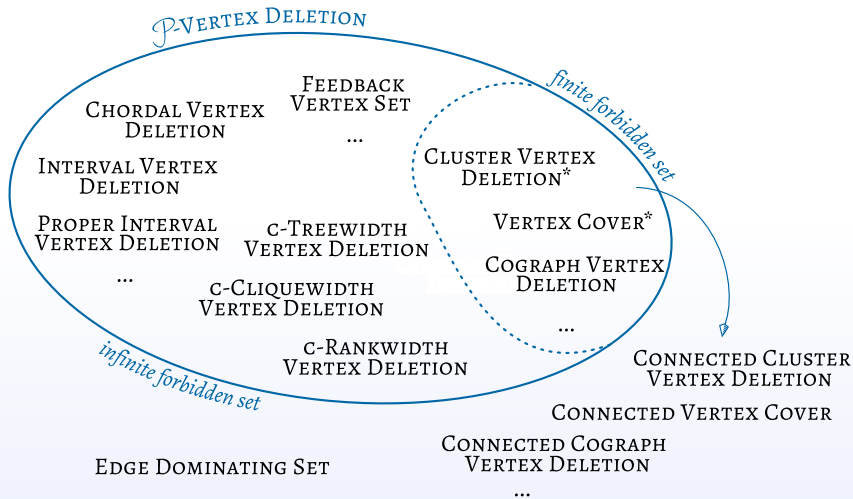
The result

We have shown that problems...

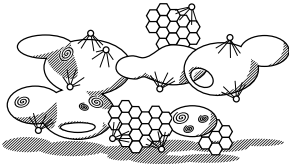
- ① ... that can be solved in polynomial time via **dynamic programming** on graphs of bounded treewidth
- ② ... that have **finite integer index**
- ③ ... and that are **treewidth bounding**

admit linear kernels on graphs excluding a fixed topological minor.

Examples

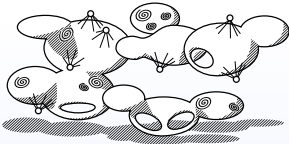


Trade-off: class of instances vs. problem requirements



*H-Topological-
Minor-Free*

Treewidth-bounding



H-Minor-Free

*Bidimensional
+ separation property*



Bounded Genus

Quasi-compact



Planar

“Distance-property”

Open questions

- What about graphs excluding a fixed *induced minor/contraction/immersion*? Which other notions of sparse graphs allow such a theorem?
- Can we do this for DOMINATING SET and similar problems? (Grohe & Marx -decomposition!)
- Are there interesting *polynomially* treewidth bounding problems? (We looked at *linear* treewidth bounding)

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Thank you!